

# Discrete Time System

**Talk to a Teacher Project**

**<http://spoken-tutorial.org>**

**National Mission on Education through ICT**

**<http://www.sakshat.ac.in>**

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# Objectives

- **Convert between state space and transfer function descriptions**



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- **Define a discrete time system and plot its Step response**



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- **Define a discrete time system and plot its Step response**
- **Discretize a continuous time system**



# System Requirements

- OS: Ubuntu Linux 12.04



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- **Scilab 5.3.3**



# Prerequisite

- **Basic knowledge of Scilab**



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- **Basic knowledge of Scilab**
- **If not, please refer to the Scilab tutorials available on <http://spoken-tutorial.org>**



# State Space Model

## The state space model



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$$\begin{aligned}\dot{x} &= Ax + Bu \\ y &= Cx + Du\end{aligned}$$



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is specified by

```
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```



# State Space Model

## The state space model

$$\begin{aligned}\dot{x} &= Ax + Bu \\ y &= Cx + Du\end{aligned}$$

is specified by

```
--> sys3 = syslin('c',A,B,C,D)
```

for prespecified matrices  $A$ ,  $B$ ,  $C$   
and  $D$  of suitable sizes



# State Space Model

Define (for example) matrices

$$A = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$C = -3B^T$$

$$D = 2$$



# State Space Model

- Check whether poles of  $\text{sys4}$  (by 'plzr')



# State Space Model

- Check whether poles of  $\text{sys4}$  (by 'plzr')
- are same as eigenvalues of  $A$  (by 'spec')



# State Space Model

**The 'ss2tf' command can be used**



# State Space Model

The 'ss2tf' command can be used

- to obtain a transfer function



# State Space Model

The 'ss2tf' command can be used

- to obtain a transfer function
- of a state-space system `sysSS`



# State Space Model

The 'ss2tf' command can be used

- to obtain a transfer function
- of a state-space system `sysSS`
- For example:

$$\rightarrow sysTF = ss2tf(sysSS)$$



# State Space Model

- Use `ss2tf` function for `sys3` defined earlier



# State Space Model

- Use `ss2tf` function for `sys3` defined earlier
- `sysTF` is a new variable for which 'denom' command is applicable (and not applicable to `sys4`)



# Exercise:

Find a state space realization of the second order transfer function defined below:



$$G(s) = \frac{9}{s^2 + 6s + 19}$$

- **Hint: use 'tf2ss'**



# Exercise:

For the new system (in state space form), say **sysSS**, check if

- The eigenvalues of the matrix  $A$  and the poles of the transfer function  $G(s)$  are the same
- Use the  $A$ ,  $B$ ,  $C$ ,  $D$  matrices of the system **sysSS** to obtain the transfer function



# Exercise:

- **Check if the answer is the original one**



# Discrete Time System

**We now define a discrete time system**

- **It is customary to use 'z' for the variable in the numerator and denominator polynomials**



# Discrete Time System

- Recall that the variable ' $z$ ' has a shortcut



# Discrete Time System

- Recall that the variable 'z' has a shortcut
  - Instead of  $z = \text{poly}(0, 'z')$



# Discrete Time System

- Recall that the variable 'z' has a shortcut
  - Instead of  $z = \text{poly}(0, 'z')$
  - Use:  $--> z = \%z$



# Discrete Time System

- We now define a first order discrete time system



# Discrete Time System

- We now define a first order discrete time system
- We use the 'syslin' function for this



# Discrete Time System

- We now define a first order discrete time system
- We use the 'syslin' function for this
- We specify the domain to be discrete time



# Discrete Time System

- We now define a first order discrete time system
- We use the 'syslin' function for this
- We specify the domain to be discrete time
- Instead of continuous time



# Discrete Time System

- For checking the step response, we have to define the input explicitly as ones



# Discrete Time System

- For checking the step response, we have to define the input explicitly as ones
- Instead of `csim`, we have to use the 'flts' function to simulate this system



# Discrete Time System

- It is helpful to discretize a given continuous time system



# Discrete Time System

- It is helpful to discretize a given continuous time system
- This is done using the `dscr` function



# Discrete Time System

Let us

- discretize the system 'sysG'



# Discrete Time System

Let us

- discretize the system 'sysG'
- with a sampling period of 0.1



# Discrete Time System

- Notice that we obtain the discretized system in state space representation



# Discrete Time System

- Notice that we obtain the discretized system in state space representation
- We can convert this to a transfer function representation in discrete time using the `ss2tf` function



# Summary

In this tutorial, we have learnt to:

- Convert between state space and transfer function descriptions
- Define a discrete time system and plot its Step response
- Discretize a continuous time system



# About the Spoken Tutorial Project

- Watch the video available at [http://spoken-tutorial.org/What\\_is\\_a\\_Spoken\\_Tutorial](http://spoken-tutorial.org/What_is_a_Spoken_Tutorial)
- It summarises the Spoken Tutorial project



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- If you do not have good bandwidth, you can download and watch it



# Spoken Tutorial Workshops

## The Spoken Tutorial Project Team

- Conducts workshops using spoken tutorials
- Gives certificates to those who pass an online test
- For more details, please write to [contact@spoken-tutorial.org](mailto:contact@spoken-tutorial.org)



# Acknowledgements

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- **It is supported by the National Mission on Education through ICT, MHRD, Government of India**
- **More information on this Mission is available at**

<http://spoken-tutorial.org/NMEICT-Intro>

