

Electromagnetism
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Lecture – 20
Vector calculus in spherical coordinate system Part - 02

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$$\nabla^2 T = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 T}{\partial \phi^2}$$

Cylindrical coordinate system

$$x = s \cos \phi$$

$$y = s \sin \phi$$

$$z = z$$

Unit vectors:

$$\hat{s} = \cos \phi \hat{x} + \sin \phi \hat{y}$$

$$\hat{\phi} = -\sin \phi \hat{x} + \cos \phi \hat{y}$$

$$\hat{z} = \hat{z}$$

Now, let us move on to the cylindrical coordinate system. In cylindrical coordinate system, we have a cylindrical symmetry. So, let us draw a cylinder to begin with. And the Cartesian coordinate system reference for this kind of a system is given as this. This is our x-axis, this is y-axis and this is the z-axis. So, from, the z-axis is very important here.

From the z-axis if we consider a point P on the surface of the cylinder, so, the distance of that point P from the z-axis we will call that s small s and the position vector of that point P is

given as r . We have if we project r on to the x y plane say the projection comes somewhere here, then that projection makes an angle with the x -axis that angle is ϕ , and the z component of that position vector is called z . So, z is also there in cylindrical coordinate system.

So, we have x equals s cosine of ϕ , y equals s sin ϕ , and z equals z . The unit vectors can be given as \hat{s} equals cosine ϕ \hat{x} cap plus sin ϕ \hat{y} cap $\hat{\phi}$ equals minus sin ϕ \hat{x} cap plus cosine ϕ \hat{y} cap and \hat{z} cap is certainly equal to \hat{z} cap in Cartesian coordinate system. So, these are the unit vectors.

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Infinitesimal displacements

$$dl_s = ds; \quad dl_\phi = s d\phi; \quad dl_z = dz$$



$$d\vec{l} = ds \hat{s} + s d\phi \hat{\phi} + dz \hat{z}$$

Volume element $d\tau = s ds d\phi dz$

$$s \in [0, \infty]; \quad \phi \in [0, 2\pi]; \quad z \in [-\infty, \infty]$$

Surface element $s d\phi \hat{\phi} \times dz \hat{z} = s d\phi dz \hat{s} \rightarrow$ on the cylindrical surface

Gradient

$$\vec{\nabla} T = \frac{\partial T}{\partial s} \hat{s} + \frac{1}{s} \frac{\partial T}{\partial \phi} \hat{\phi} + \frac{\partial T}{\partial z} \hat{z}$$



Now, let us consider the infinitesimal displacement for line element. Along s direction an infinitesimal displacement dl_s will be given as ds ; along the ϕ direction dl_ϕ can be given

because this is an angle as $s \, d\phi$ and along the z direction is simple dz . So, the line element dl can be expressed as $ds \hat{s} + s \, d\phi \hat{\phi} + dz \hat{z}$, it is simple.

Let us consider the volume element volume element $d\tau$ would be given as multiplication of all these components that is $s \, ds \, d\phi \, dz$. We have to consider that s belongs to the range 0 to infinity, ϕ belongs to the range 0 to 2π , and z just like the Cartesian coordinate system belongs to the range minus infinity to infinity.

Now, if we consider a surface element, let us draw a cylinder here, and if we consider a surface element on this cylindrical surface, then the distance is s from this axis that is z -axis, and we will rotate it by an element $d\phi$. So, the distance that will travel that it will travel along the surface is $s \, d\phi$ along the ϕ direction. And the other component would be dz components, so $dz \hat{z}$ and this will give us $s \, d\phi \, dz$, and the direction of this surface element would be \hat{s} in this notation. So, this is a surface element on the cylindrical surface.

We can find out other surface elements in a similar way. Let us move onto writing down the expressions for gradient, divergence, curl and Laplacian. The expression for gradient is gradient of a scalar field T is given as $\nabla T = \hat{s} \frac{1}{s} \frac{\partial T}{\partial s} + \hat{\phi} \frac{1}{s} \frac{\partial T}{\partial \phi} + \hat{z} \frac{\partial T}{\partial z}$.

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Divergence

$$\vec{\nabla} \cdot \vec{v} = \frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$$

Curl

$$\vec{\nabla} \times \vec{v} = \left[\frac{1}{s} \frac{\partial v_z}{\partial \phi} - \frac{\partial v_\phi}{\partial z} \right] \hat{s} + \left[\frac{\partial v_s}{\partial z} - \frac{\partial v_z}{\partial s} \right] \hat{\phi} + \frac{1}{s} \left[\frac{\partial}{\partial s} (s v_\phi) - \frac{\partial v_s}{\partial \phi} \right] \hat{z}$$

Laplacian

$$\nabla^2 T = \frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial T}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 T}{\partial \phi^2} + \frac{\partial^2 T}{\partial z^2}$$


For divergence of a vector field v in cylindrical coordinate system, the expression can be given as $\frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$. For curl on the expression is curl of a vector field v is given as $\left[\frac{1}{s} \frac{\partial v_z}{\partial \phi} - \frac{\partial v_\phi}{\partial z} \right] \hat{s} + \left[\frac{\partial v_s}{\partial z} - \frac{\partial v_z}{\partial s} \right] \hat{\phi} + \frac{1}{s} \left[\frac{\partial}{\partial s} (s v_\phi) - \frac{\partial v_s}{\partial \phi} \right] \hat{z}$. The Laplacian in cylindrical coordinate system acting on a scalar field T is given as $\frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial T}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 T}{\partial \phi^2} + \frac{\partial^2 T}{\partial z^2}$.