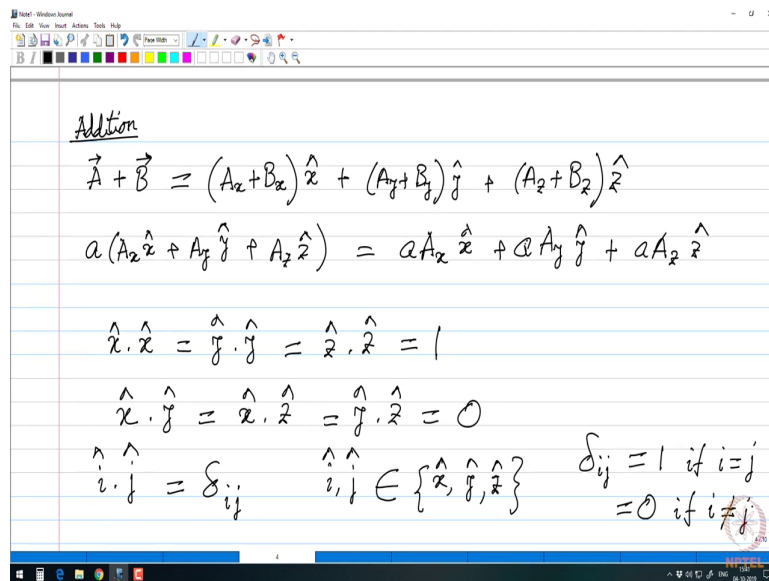


Electromagnetism
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Lecture - 02
Vector algebra in component form

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Now, how do we add two vectors in this component form? If we have vector A and vector B we want to add them two and A has x, y and z components A x, A y and A z. B has B x, B y and B z. So, this in the component form can be written as A x plus B x x cap plus A y plus B y y cap plus A z plus B z z cap.

How do we multiply a scalar with a vector in written in its component form? A scalar a is multiplied with a vector A x x cap plus A y y cap plus A z z cap that just gives a this vector. So, we have in Cartesian coordinate system x cap, y cap and z cap they are mutually

perpendicular, these are orthogonal vectors and the magnitude of all these vectors that unit vectors is 1.

Therefore, we have $\hat{x} \cdot \hat{x} = \hat{y} \cdot \hat{y} = \hat{z} \cdot \hat{z} = 1$ and if we take dot product of two different unit vectors that is $\hat{x} \cdot \hat{y}$ that is equals $\hat{x} \cdot \hat{z}$ that equals $\hat{y} \cdot \hat{z}$ that always becomes 0. So, in a more compact notation we can write $\hat{i} \cdot \hat{j} = \delta_{ij}$.

Now, i and j can take values from x, y and z . So, we can write i, j belongs to the set x, y, z and Kronecker delta function is defined as this is 1 if i equals j is 0, if i not equals j that is the definition of Kronecker delta.

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The image shows a handwritten derivation on a digital whiteboard. The text is as follows:

$$\vec{A} \cdot \vec{B} = (A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) \cdot (B_x \hat{x} + B_y \hat{y} + B_z \hat{z})$$
$$= A_x B_x + 0 + 0 + A_y B_y + A_z B_z$$
$$= A_x B_x + A_y B_y + A_z B_z$$
$$\vec{A} \cdot \vec{A} = A_x^2 + A_y^2 + A_z^2$$
$$|\vec{A}| = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

The whiteboard interface includes a menu bar (File, Edit, View, Insert, Actions, Tools, Help), a toolbar with drawing tools, and a Windows taskbar at the bottom with the date 04-12-2019.

Accordingly, now if we make a dot product of A and B; so, $A \cdot B$ where A and B are written in component form. So, that is written as $A_x \hat{x} + A_y \hat{y} + A_z \hat{z}$ dot $B_x \hat{x} + B_y \hat{y} + B_z \hat{z}$.

Now, if we take a dot product between this part and this part, we obtain $A_x B_x$. If we take a dot product between this part and this part because the dot product of \hat{x} and \hat{y} goes to 0, we get 0 here and for the next one also we get. So, the dot product between $A_x \hat{x}$ and $B_z \hat{z}$ that also becomes 0 then we come to $A_y \hat{y}$ it is dot product with $B_x \hat{x}$ goes to 0. The dot product that sustains is $B_y \hat{y}$.

So, with for that we get $A_y B_y$ and the dot product with $B_z \hat{z}$ for $A_y \hat{y}$ also goes to 0. Similarly, for $A_z \hat{z}$ we will have only the dot product sustaining is with $B_z \hat{z}$. So, we get here $A_z B_z$; that means, the dot product that we are interested in becomes $A_x B_x + A_y B_y + A_z B_z$.

Now, if we take a dot product of vector A with itself, $A \cdot A$ what do we get as a result. That will looking at the example earlier we can write that it would become $A_x^2 + A_y^2 + A_z^2$. If that is the case then we can write that the magnitude of the vector A is actually square root of this part, $\sqrt{A_x^2 + A_y^2 + A_z^2}$.

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The image shows a digital whiteboard with handwritten mathematical derivations. At the top, it is titled "Cross product". Below the title, three equations are listed, grouped by a large right-facing curly brace:

$$\hat{x} \times \hat{x} = 0 = \hat{y} \times \hat{y} = \hat{z} \times \hat{z}$$

$$\hat{x} \times \hat{y} = -\hat{y} \times \hat{x} = \hat{z}$$

$$\hat{y} \times \hat{z} = -\hat{z} \times \hat{y} = \hat{x}$$

$$\hat{z} \times \hat{x} = -\hat{x} \times \hat{z} = \hat{y}$$

Below the brace, the cross product of two vectors \vec{A} and \vec{B} is derived:

$$\vec{A} \times \vec{B} = (A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) \times (B_x \hat{x} + B_y \hat{y} + B_z \hat{z})$$

$$= (A_y B_z - A_z B_y) \hat{x} + (A_z B_x - A_x B_z) \hat{y} + (A_x B_y - A_y B_x) \hat{z}$$

Now let us go for cross product in this component form because with cross product we get a vector perpendicular to the plane therefore, $\hat{x} \times \hat{x}$ becomes 0. Similarly, $\hat{y} \times \hat{y}$ and $\hat{z} \times \hat{z}$ are also 0. If we take $\hat{x} \times \hat{y}$ that is minus $\hat{y} \times \hat{x}$ as we have found out for any two vectors earlier and this equals \hat{z} in orthogonal Cartesian coordinate system.

Similarly, $\hat{y} \times \hat{z}$ equals minus $\hat{z} \times \hat{y}$ equals \hat{x} and $\hat{z} \times \hat{x}$ equals minus $\hat{x} \times \hat{z}$ equals \hat{y} . This will be useful later for performing any cross product. So, if we now perform a cross product between two vectors A and B, we can write it as $A_x \hat{x} + A_y \hat{y} + A_z \hat{z} \times B_x \hat{x} + B_y \hat{y} + B_z \hat{z}$ and that becomes going by the rules that we have set here. $A_y B_z - A_z B_y \hat{x} + A_z B_x - A_x B_z \hat{y} + A_x B_y - A_y B_x \hat{z}$.

Now, this expression so, the way we have performed cross product is by going through the relations we have set here in above, but there is a better way to remember it and represent it in a compact form that is by making a determinant.

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In determinant form

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Example

Find the angle between \vec{A} and \vec{B} .

$$\vec{A} = 1\hat{x} + 0\hat{y} + 1\hat{z}$$

$$\vec{B} = 0\hat{x} + 1\hat{y} + 1\hat{z}$$

The image shows a 3D coordinate system with x, y, and z axes. A cube is drawn with one corner at the origin. Two vectors, A and B, are shown originating from the origin. Vector A points to the top-back corner of the cube, and vector B points to the top-right corner. The angle between them is labeled as theta.

So, the cross product can be written in a determinant form as follows. A cross B with its Cartesian components can be written as a determinant $\hat{x} \hat{y} \hat{z}$; $A_x A_y A_z$, $B_x B_y B_z$ this determinant. Let us see an example, let us consider a cube of arm length one in Cartesian coordinate system. Here is our Cartesian coordinate system these are the axis x, y and z. So, this much is arm length one. So, we have the cube like this, here is the cube. And we have two vectors, this is vector A and here is vector B. We want to find the angle between these two vectors; that means, this angle let us call it theta.

So, let us write down A in its coordinate form, if we look at it we can see that A projected onto x axis will give us 1; that means, its x component is 1. Projected onto y axis there is no projection it is 0 and if we project it on to z axis that is also 1. So, this is the expression, this is the component form for A vector. For B vector the component form would look like its projection onto x axis is 0. So, 0 plus projection onto y is 1, so 1 and projection on to z is also 1. So, 1 this is the form of B vector.

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The image shows a digital whiteboard with the following handwritten content:

$$\vec{A} \cdot \vec{B} = 1 \cdot 0 + 0 \cdot 1 + 1 \cdot 1 = 1$$

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$A = \sqrt{1^2 + 0^2 + 1^2} = \sqrt{2}$$

$$B = \sqrt{0^2 + 1^2 + 1^2} = \sqrt{2}$$

$$\sqrt{2} \sqrt{2} \cos \theta = 2 \cos \theta = 1$$

$$\cos \theta = \frac{1}{2} \quad \theta = 60^\circ$$

Now, if we perform a dot product of A and B using the component forms that we have just deduced. We have this A dot B equals 1 dot 0 plus 0 dot 1 plus 1 dot 1; that means, its 1 and we know that A dot B equals A B cosine of the angle between them. So, let us find out the magnitude of A vector A that is given as 1 squared plus 0 squared plus 1 squared square root of this entire thing that is square root of 2.

For B vector the magnitude is also the same $0^2 + 1^2 + 1^2$ square root of this equals square root of 2. And now applying this equation here we find that square root 2 times square root 2 times cosine of the angle, that is $2 \cos \theta = 1$. And if $2 \cos \theta = 1$; that means, $\cos \theta = \frac{1}{2}$ that gives us $\theta = 60^\circ$.