Advanced Machining Processes Prof. Shantanu Bhattacharya Department of Mechanical Engineering Indian Institute of Technology, Kanpur Week - 04 Lecture - 09 Electrochemical Machining-II

So, a brief recap of what we did last time, we studied about electrode double layer theory, the expression for the zeta potential we tried to derive with respect to an electrode where zeta potential is the potential which is generated by any surface which comes in contact, solid surface coming in contact with the solution. And then we, of course, modelled electrically the double layer tried to understand how potential varies with respect to distance x in a single direction from the electrode. And then of course, we started understanding some of the basic electrochemistry behind the electrochemical machining process ECM process. And as such started deriving things like material removal rate etcetera by Faraday's laws of electrolysis. So, today we have just an extension of that. So, what we started doing is understanding how mass flow rate in terms of deposition or dissolution on electrochemical process would happen and it is given by the Faraday's law.

Where the Faraday's law says that the total amount of mass removed is proportional to the current that is passed through the solution, the time for which it is passed, and something called epsilon where epsilon is this electrochemical or the atomic weight equivalent or equivalent atomic weight of particular species. Which means in turn that 1 mole of a species whose weight is the atomic weight A of a valency Z. So, of Z valent states would have an equivalent weight epsilon of A by Z. That means, it is something like the amount of charge which would be needed to remove so much amount of weight.

So, it gives an indication of that. And so basically that is what the atomic the equivalent atomic weight epsilon is. And of course, current time product is basically the amount of charge which is sent into the system, the electrochemical system which does either dissolution or deposition in as in an electrochemical process. So, here we can always say that the mass removal rate that is m dot as can be illustrated in this formula here is actually equal to the amount of equivalent weight that a person or that a material would have that is A by Z times of an idea of what is the how many number of moles of current which is charge per minute time dq by dt is flown into the system. So, the charge per unit time which is flown into the system in terms of number of moles of charge.

So, moles of charge per unit time. So, this is given by the term I by F where F as I already mentioned is this 96500 coulomb which is actually the charge of 1-mole electrons 6.023 10 to the power of 23 times of 1.6 10 to the power of minus 19 this is the charge on 1 electron. So, 1 mole electrons would have total charge of 96500 coulombs.

So, that is what the Faraday F term would be in this process. So, I by F is really indicative of the number of moles of charges per unit time which flows into the system. So, and if so many moles of charges are really needed A by Z charges are needed for this amount of grams which is coming out. So, A Z by A by Z times of I by F would actually give the amount of mass rate of removal the amount of mass which is coming out. So, in terms of if you include the density factor rho of the

anode in grams per centimetre cube the mass flow rate and density equated together would result in the volume flow rate.

So, Q is actually m dot by rho which is equal to Ai by rho Z F and this is in centimetre cube per second this is the volume rate of removal of a material of an electrochemical process. So, this is very-very standard formulation of how Faraday's laws can be utilized in actually trying to find out what is the material rate of removal of some particular electrode which is deposited, or which is actually stationed in some solution. So, this is true so for a single-phase system where there are not multiple components or multiple metals which are involved in the electrode it is of a single metal or single material or the removal that you are doing on single material. However, in engineering situations in real-life problems really you are actually not working on direct metals, but on alloys, because alloying actually improves the system properties and engineering materials are really alloyed compositions most of the time. And so, therefore, this extension of this electrochemical basis of material removal has to be in an alloyed system as all where there is not a single phase as 1 metal, but variety of phases in mixture with each other.

So, you will have different atomic weights of these phases, you will have different densities of these phases which are in dissolution. And therefore, a complex system emerges because of the application of this straightforward single metal case into that alloyed system. So, let us look at a problem example of that sort as mentioned here. So, let us say the anode now is made up of an alloy instead of a pure metal and the removal rate can be found by considering the charge required to remove an unit volume of each element. So, if the atomic weights and valencies of the corresponding ions entering the electrolyte are A1, A2, A3 so on and Z1, Z2, Z3 so on respectively.



The composition by weight of the alloy let us say is X1 percent of the element 1 which has an atomic weight of A1 and valency in which it comes out as Z1. So, this is the valency state which actually comes into question when this material gets removed from the particular electrode. The atomic weight A2 and its valency Z2, the atomic weight A3 its valency Z3 so on so forth respectively. And the composition by weight of this alloy is may be let us say X1 percent of A1, X2 percent of A2, X3 percent of A3 so on so forth. And the whole idea is about the removal of a volume v centimetre cube of this alloy where all these paradigms need to be somehow integrated.

So, that total amount of volume that is removed is v-centimetre cube. And how much will that contain in terms of the mass. So, if v centimetre cube is the total volume of the material that is to be removed. So, the amount of mass that it would contain would actually be v rho where rho is the average density. And this is something we need to find out in a practical application I will just let you know once we do a numerical problem.

So, average density of the alloyed system. So, v rho is basically the total amount of mass which is contained in v centimetre cube volume and out of which as I have already told the system has different species of atomic weights A1, A2, A3 of different valencies Z1, Z2, Z3 so on up to you know some n may be component. And then in different percentages X1, X2, X3 so on so forth. So, therefore, is the total amount of contribution in the mass v rho coming out of the ith metal right. Let us say so on so forth you have a case where you have the ith metal of percentage Xi with the valency Zi and atomic weight equivalent I mean atomic weight of Ai.

So, the ith metal this formulation so-called would get converted into v rho Xi by 100. So, this much is the mass contribution of the ith metal in the total mass v rho of the alloyed system where we assume that v volume centimetre cube or v-centimetre cube of volume is coming out of the system. So, this is the mass in grams of the ith element. And we need to somehow develop a strategy to calculate this overall average density of the whole alloyed system. And this will come in practical application where you can compare the densities of the different components of a system and try to somehow average it at looking at the different percentage contributions that those independent elements corresponding to, I equal to some value would have in the overall system.

So, the amount of charge that is required to move the ith element in the volume v is given by the formulation. This mass removal times of Zi F by Ai and that is so because of the fact that if this were the mass of the ith system. So, the amount of moles which are there in this mass assuming Ai to be the atomic weight of this particular system would be given by v rho Xi by 100 times of Ai. And so many moles need to be removed meaning thereby that these are at Zi valency state meaning thereby the amount of charge that would be needed to be removed is so many moles' times of the valency state. So, so many electrons or so many moles of electrons would be needed to remove this charge.

So, the amount of charge that is required to remove the total charge that is required to remove this metal in material, total charge required to remove this material would be v rho Xi Zi by 100 Ai times of the total charge in 1-mole electrons that is F 96500 coulombs. So, that is the overall charge which is needed to remove the ith element in the volume v of the given alloy composition. So, obviously, if this is the charge per unit volume, the volume per unit charge would simply be a reciprocal of this. And therefore, the volume per unit charge of the alloy removed per unit charge is given by this formulation right here which is simply a reciprocal of this term here.

So, cut. So, amount of volume of the alloy removed per unit charge is simply given by the formulation just the inverse of whatever is mentioned here. And that is basically can be represented as 1 by v rho Xi divided by 100 times of Zi F by Ai, cut. So, therefore, the volume of the alloy removed per unit charge is basically the reciprocal of this as I mentioned before right mentioned earlier is just simply the reciprocal of this particular term as you can see here. So, let us just look at what the reciprocal would be like. So, we have 1 divided by v rho Xi by 100 times of Zi F by

Ai. Ai is this i is the subscript. So, the ith element in the alloyed system.

So, this can be further written down as rho by sorry 100 by rho F these really are constants this is the average density of the alloyed system. This F is having a value 1 mole charge of 1 mole electrons which is 96500 coulombs. So, you can consider these outside the whole you know variable terms or outside the scope of the variable terms.

And the other part basically is 1 divided by volume times of Zi Xi divided by Ai. And for v volume, because total removal is a v-centimetre cube the amount of charge that would be needed is really v for a unit volume this is the charge which is needed right. The total volume v centimetre cube would be v divided by this value here right v divided by v rho Xi by 100 times of Zi F Ai. So, this really goes to a situation where this v is eliminated because it is per unit v volume. And the total amount of charge so needed per unit volume is 1 by or 100 by rho F times of sigma Xi Zi time divided by Ai right.

Why sigma? Because as you know that there are i components and this i varies between 1 and n. So, really looking at individualistic components where i can be 1 to n. The total so-called volume of alloy removed per unit charge can be represented as this whole term 100 by rho F 1 by sigma Xi Zi by Ai. There are certain connotations you can use here. For example, if you put the value of F here as 96500 the 100 by F term comes out to be about 0.1035 10 to the power minus 2 as rho value. And then this whole 1 by sigma Xi Zi by Ai is the total amount of volume of the alloy removed per unit charge. Volume unit is a centimetre cube and charge is ampere second and that is how that is the amount of you know this very critical for the whole electrochemical operation of an alloy. So, let us look at a practical alloying system and try to see how to calculate this rho average of the alloy and how to calculate overall the volume of the alloy removed per unit charge that is given. So, to begin with let us look at an electrochemical machining process with pure iron workpiece where a removal rate of 5-centimetre cube per minute is desired and we will have to determine how much current would be needed in a ECM process for that.

Numerical problemIn an electrochemical machining process with a pure iron work-piece, a removal
rate of 5 cm³/min. is desired. Determine the current required.The gram alomic arcight, Valence
a-which dissolution lakes place, and
dersoily option are 56gms, $2 & 2 & 7 & 83/a^3$
Verp. $\frac{5}{60} = \frac{56 \times \tilde{T}}{7.8 \times 2 \times 96500}$

So, let us say if we look at the gram atomic weights table. So, the gram atomic weight and of course, the valency state of dissolution and also the density comes from the standard tables as for particularly for iron because iron is the material to be removed comes out to be equal to 56 grams. Mostly iron goes in the divalent state. So, Z equal to plus 2 and then the density of iron happens to be about 7.8 gram per centimetre cube. We already know that m dot or the material removal rate is given by an expression Ai by ZF. This is a pure alloy; this is a pure system there is no alloying component as such and this m dot is also expressed in terms of volume rate of removal q as Ai by rho ZF this is in centimetre cube per second, and we have our volume removal rate which is intended in per minutes. So, we have 5 by 60-centimetre cube per second should be equal to the atomic weight of iron which is 56 grams times of the current desired which we need to find out divided by the density 7.8 grams per centimetre cube times of the valency state. So, it comes as a divalent dissolution and of course, the Faraday value which is 96500 coulombs.

In other words, calculating this for i you get a very i value of about 22000, 2240 amps. So, what I want to bring to your notice is that a very small removal rate of only 5-centimetre cube per minute which is actually very small in terms of conventional machining processes that machining would happen. In this electrochemical machining a such a high current value is needed about 2300 amperes is needed 2.3 kilo amps. So, again it proves out that whether it is a mechanical process or whether it is a chemical process or electrochemical process.

In general, these advanced manufacturing methods do have a very high energy requirement, but of course, there are connotations like you know being able to produce complex shapes or being able to produce the desired roughness's which allows us to use these methods over some of the conventional strategies which are widely available. So, that is the utility of be it electrochemical machining, be it abrasive jet machining, be it ultrasonic machining, or any other non-conventional so-called advanced manufacturing domain. So, the main key is the complexity which you have to take into account for a design for manufacturing it, and the main key also sometimes is the surface toughness of the surface finish of a particular part. And that is why non-conventional or advanced and that is why the utility of such machining fabrication regimes for microsystems engineering and microsystems design and fabrication. So, let us look at another alloyed system as I just told.

So, and just before you know looking at an alloyed system there are certain other very fundamental level things which need to be taken care of. So, the first thing that I would like to tell here is that in an actual ECM process there you know the many other factors also which remove, or which influence the material removal rate. And if you look at really a simile between the actual removal rates given by these dots here and the theoretically predicted rates given by the straight line there is some variation some level of variation. And one of the main reasons is that the sometimes you know the theoretical removal rates are only based on one prominently available valency states of the material. But actually, it may happen that the material may come out in more than 1 valency states.

For example, iron can exist as a ferric state plus 3 or ferrous plus 2, or in case copper may exist as a plus 2 cuprous or a plus 3 cupric states. And so, the theoretical predictions really do not take care of or do not account for what is the valency state which is coming out of the ECM process. And therefore, you know sometimes the theoretically predicted rates may not tally very well with the actual rates. The actual rates may be slightly lower because of multiple valency states which may

be coming out of such a system. So, that is what 1 aspect is or what has to be considered for any let us say electrochemical machining process.

The other aspect of course, is the alloyed system as I told. And standard tables like these are very easy or very convenient to look at you know in a nutshell what all the different states are of a particular material or how they will come out. And also, what is the corresponding equivalent density or a gram atomic weight of a particular material. And so, these tables would be off and on use throughout this lecture and even beyond for predicting some of the material removal rates from a fundamental standpoint. So, now let us look at the alloyed system as I promised.

So, we have a composition called Nimonic 75 alloy here which is very often used, and ECM is performed off and on. So, the composition is given right here in this table. So, you have all different phases in the alloyed system nickel, chromium, iron, titanium, silicon, manganese, and copper. And what these numbers are basically they mention about the different percentages of presence of these different states like this is corresponding to Xi for the nickel state, this is Xi for the chromium. So, called for the you know 5 percent is the amount at in which iron is present, 0.4 percent is an amount in which titanium in present so on so forth.

So, we need to calculate the removal rate in such a complex system alloyed system using the theory we have developed just now. And the prediction has to be in centimetre cube per minute the rate of material removal. And the only thing given to us is that the current of 1000 amperes is passed, and we want to use just the lowest valency of dissolution of each element. Although when predicting actual rates may be different because of as I told you multiple valence states coming out the dissolution process.

So, what do we do here? So, the first thing that comes to our mind is what the material removal of an alloying system would be and the removal rate as we just about derived and found out in the last 1 or 2 slides in centimetre cube per unit charge per second is given by 0.1035 10 to the power of minus 2 that is about 1 by the farad 96500-coulomb times the rho average and this average is something we have to find out times of 1 by sigma Xi Zi by Ai. And so, this rho average is something that we need to determine for the particular alloy. So, what is rho average or how do we determine it? So, the average density can be really found out by looking at what is the total weight which is removed. So, let us say if W is the total weight of the electrode that is dissolved and this W has components X1, X2, X3 so on so forth percentage wise of materials with atomic weight A1, A2, A3 so on so forth with the valence states the lowest valence states Z1, Z2, Z3 so on so forth.

So therefore, the total amount of and of course, the densities are rho 1, rho 2, rho 3 so on so forth. So, the total amount of component corresponding to i equal to 1 which is present in this W is essentially Xi W or X1 W by 100 for ith component it is Xi W by 100. The total volume of the material which is present there is the total weight which is present divided by the density. So, for the ith component, the total volume which comes out coupled in this weight W is basically Xi W divided by 100 rho i. So, if I assume that the alloy essentially composes or is composed of all phases i's.

We can say that the total volume coming out is actually given by sigma Xi W by 100 rho i where

i varies from 1 to N may be there are about 1 phase or N phases of different materials and the total weight you already know is W. So, the average density can thus be recorded as the total weight divided by the total volume which is coming out which is corresponding to i equal to 1 to N Xi W by 100 rho i. In just you know little simpler version can be 100 divided by sigma Xi by rho i where i can vary between 1 to N system. So, that is how the average density can be obtained. So, I would like to state here that in our case particularly because we have almost 7 complete phases as you can see here 1, 2, 3, 4, 5, 6, 7 phases with different percentages and different of course, densities different atomic weights so on so forth.

So, the total amount of rho in our case given by this 100 by sigma i Xi by rho i can be represented as 100 divided by the first percentage that is percentage nickel 75, 72.5 percent in the mnemonic alloy divided by the density of nickel which is 8.9 gram per centimetre cube plus that of the second phase which is chromium third place is iron. You can see these different phases here titanium fourth is silicon, manganese and copper. So, it is basically percentage of iron divided by density of iron plus percentage of the third phase by density of the third phase plus that of the fourth phase by density of the fourth phase plus fifth plus sixth plus seventh.

So, the average density, in this case, can be calculated as 8.18 grams per centimetre cube. So, once the rho average is calculated then of course, the material removal rate or the volume per unit charge that you may have already seen before in can be determined as 0.1035 10 to the power of minus 2 by this rho average value which we have just calculated divided by 1 or multiplied by 1 times of sigma Xi Zi by Ai. And this i basically varies between again 1 to 7 in our case.

So, this can be written down here as 72.5 percentage Xi equal to 1 times of the valency state the lowest valency state for nickel in which it comes out is 2. We have to take the lowest valency state divided by the atomic weight of nickel which is 58.71 plus that for chromium plus that for the third phase plus that for the fourth phase plus that for the fifth phase sixth and seventh phases respectively. And if you really look at the overall value here it comes out to be equal to 0.35 10 to the power of minus 4 volume per unit charge centimetre cube per ampere second.

And obviously, when 1000 ampere current is used the removal rate that is the amount of material coming per unit time is given by whatever this amount is times of charge per unit time or current. So, the Q dot the material removal rate in this particular case would come out to be equal to the current value which is 1000 amps. And we want to estimate the material removal rate in centimetre per minute. So, therefore, whatever value we have we will have to multiply that by 60. So, this is charge per unit seconds and this would be charge per unit minute times of however, volume whatever volume comes per unit charge which is 0.35 10 to the power of minus 4 as you can see from here and this becomes 2.1-centimetre cube per minute.

So, again a very small amount corresponding to about a 1 kilo amp current, and because it is an alloyed system you have taken care of all the participants of the alloy you know participating in the in making the electrode in this particular system. And so, therefore, this is a very nice way of estimating for particularly alloyed systems the material removal rate. What I would now like to point out is again you know something related to how the potential would get distributed between the cathode and the anode once it is made a part of the electrochemical cell.

And for doing that we need to somehow look into the profile of the potential with respect to the inter-electrode spacing or distance between the electrodes in such a system. So, let us look at that in details. So, if you look at the way that potential varies from the anode side in this case this is the anode potential to the cathode side. So, as I have already told before that the workpiece is made the anode and the tool is made the cathode in this particular machining operation. So, therefore, the relationship between the voltage applied across the electrodes and the flow of current has a lot of you know effects due to which the potential may get changed particularly because of the formation of dual layer, particularly because of the formation of migration, particularly because of the formation of a resistive drop this potential has substantial changes between one electrode and another.



So, let us look at what all are the total components of such a potential profile which would be

created in meaning thereby that what are the components which would cause the potential to drop as coming from anode to cathode. So, one of course, is the overall electrode potential which is the anode of the cathode potential. The second component is a drop which is because of a sort of activation polarization. What that means typically is that the electrochemical changes are in equilibrium when no current flows and there is a barrier potential which is also the zeta potential, we have developed a lot of formulations on this before. And this basically is a barrier to a faster rate of reaction and this barrier has to be crossed.

So, the zeta potential barrier which has been made has to be crossed in order for the ions to start exchanging with the solution. So, an additional energy has to be supplied to get the required MRR. So, this is a over-voltage, therefore. So, whenever you are planning a certain voltage resulting in certain current you will have to accommodate for these over voltages and supply a slightly higher voltage. So, that these losses can be taken care of while doing electrochemical machining.

The second reason for potential drop is concentration polarization which happens because ions migrate towards the electrodes of opposite polarities. And there is a gradient of concentration which is created near any electrode surface because closest to the electrode the ion density would be maximum and as you move away from the electrode the ion density would be minimum. So, there is always a concentration gradient. And therefore, this creates a sort of polarizing effect because there is a slightly higher density and a very low density and there is a gradient which is existing. So, automatically there is a potential which is generated because of this sort of distribution of charges in a solution space.

And this also needs to be added on to the overall electrode potential because this is typically a drop, and this drop needs to be given externally from the circuit. So, you have over voltage due to activation polarization, you have a concentration polarization over voltage which you are contributing to the overall design voltage that you are applying. And then of course, you have ohmic over voltage which is because of the formation of thin films of solid materials. As you know that a electrochemical process sometimes really very close to the electrode deposits a very small layer of metal. Although the purpose of the whole machining operation is to be able to immediately form precipitate from the debris which gets generated of the machining.

But then 100 percent precipitation may not happen and there may be a small layer of you know solid film which gets developed or generated which would create of course, a over voltage effect. So, that barrier has to be crossed it has a resistive drop component the potential drops down and that extra potential has to be supplied on to the overall design voltage that you are giving to the flow cell electrochemical cell. So, these overvoltage ohmic in nature are because of films of solid materials forming on the electrode surface. And therefore, an extra resistance would happen to the passage of the current through this surface or close to the surface.

So, the ohmic resistance finally, plays a role also in the solution side. And therefore, there is, of course, a ohmic resistive drop of the electrolyte itself which would change majority of the potential function which is available from 1 electrode's potential to the other electrode's potential. So, this is across the bulk of the electrolyte. So, if you plot all these different potentials or potential reasons for you know the potential drops reasons 1 to 5 in a plot. And see how this potential varies as a you know the distance inter-electrode distance or electrode-electrode spacing.

So, you can see that this starts with anode potential here. And then there is a component which is added because of activation polarization this is due to the formation of that stable layer which is also the zeta potential of the electrode surface. Then of course, the ohmic overvoltage which is a sort of V equal to IR drop the ohmic over voltage is because of the thin films solid films formulated at the electrode's extra depositions. And then there is a concentration polarization over voltage because there exists a gradient of concentration. And so, that results in the whole anode overvoltage. And then of course, the amount of voltage that is available to you at the end of all this after overriding these potential functions or over-voltages is V minus delta V, where delta-V is a ensemble of all these different over-voltage potentials.

So, V minus delta V available here now goes from 1 side to the other all the way to the cathode. And so, drop there in across the bulk of the electrolyte in this region is called the ohmic resistance of the electrolyte. So, there is a V equal to IR relationship again and then it goes to the cathode side and a similar set of delta V's or over voltage functions are met at the cathode side. Thus, there is a equivalent V minus delta V which is formulated as a result of electrochemical machining.

So, that is how you can categorize the whole system of ECM. Therefore, the current which actually comes out now, because of the electrochemical transport is given by the design voltage minus the over-voltage per unit resistance of the bulk of the electrolyte and R is the resistance of the electrolyte. We could have considered the conductivities of the tool and the workpiece, but they are simply much larger in comparison to that of the electrolyte. So, the overall resistance which really comes is because of the electrolyte and not the solid metals. So, we really do not consider, we consider electrode to be a sort of potential sink or a potential source for charges. And we do not consider what happens within the electrode in terms of its own drops or own resistivities.

The conductivities are simply too high to be compared with the conductivity of the electrolyte solution. So, whatever is the conductivity of the electrolyte is a standalone conductivity which is available for the purpose of calculation of current in an electrochemical cell. So, typical electrolyte conductivities for example, vary between 0.1-to-1.0-ohm inverse centimetre inverse. And if on a comparative basis you compare the conductivities of let us say iron which can be an electrode it is about 10 to the power 5. So, you can see there is a difference of about close to 10 to the power 5 to 10 to the power 6 in terms of the conductivity values. So, iron is not matter able, what is matter able is this conductivity. So, the surfaces of the tool and workpiece can be considered as by and large equipotential, because the conductivity is simply are too high.

And the conductivity of electrolyte is not constant rather it varies with temperature. And as we will see later on, we will have a design problem where we will try to design the flow rates of the electrolytes flowing between a cathode and an anode. And there you can find out that how important or how critical temperature is. So, you will have to design the whole system based on whether the overall temperature of the system will hit the boiling point of the electrolyte which is actually a design fault. So, therefore, the conductivity varies truly with temperature and there is a relationship which gets generated, because there is a sort of you know coefficient of thermal coefficient or temperature coefficient associated with the conductivity value of an electrolyte. And we will put that in place when we come to that those calculations and somehow try to see what or how the MRR would be influenced, because of these temperature variations of conductivities locally to an electrode or may be into the bulk of the electrolyte.

So, let us look now at a very interesting aspect of the how the electrode and the tools would behave with respect to each other or in relation to one another in terms of dissolution and in terms of distance change between both the surfaces. As I already mentioned the work piece in an electrolyte or in an ECM process is always made the anode thereby meaning it is connected to the positive potential and the tool is made the cathode connected to the negative potential. And in this particular system let us say we are considering a tool which is an electrode and the workpiece where workpiece and there is a relative motion between the tool and the workpiece in the y direction. The flow of the electrolyte happens at a velocity v from this end right here to this end. So, the flow is in this direction of the electrolyte, and we want to model how this system works, because there would be a dissolution component associated with the workpiece and there would be a relative motion between the workpiece and there would be a relative motion.

And so there should be some kinematics taking place between this dissolution which is receiving away a surface and the approach of the workpiece towards the tool. So, in this case we are assuming that the workpiece is moving towards the tool. So, the work is fed here with the constant velocity which we call F basically the feed rate. So, we are feeding the workpiece in the minus y direction thereby meaning that the work is approaching the tool surface in the negative y direction. And we consider a 1-dimensional problem here and try to find out what is the correlation between the dissolution and the velocity.



So, we already know that the volume rate of removal of the material workpiece material is given by Ai divided by rho Z F, A being the atomic number, I being the current in amperes, rho is the density of the material to be removed, Z and F are the valency states and the Faraday constant respectively for the workpiece material. So, if the total over voltage function which is available is delta V meaning thereby that V minus delta V is the available voltage to us. Then we have a relationship between the electric field and the current. So, you know that V equal to I R and if we just manipulate it a little bit we can write these as 1 by k l by A where l is the length, A is the area of cross section, k is the conductivity. And therefore, we can easily convert this into a situation where V by l which is also the electric field, electric field is actually equal to I by k A and this I by A is nothing but the current density J by k.

So, therefore, the J in this case can be represented as this V minus delta V which is the obtained voltage provide per unit the distance of separation between the work and the tool at any given instance of time let it be y t its function of time. So, this is the field which is available and the local conductivity assuming the whole process to be done at a constant temperature right now, just for simplicity's sake we would do that comes out to be k V minus delta V by y t. So, that is how the current density term in this whole electrochemical machining business would come out to be. Now, the removal of the work material causes the workpiece surface to recede in the y direction and this is with respect to the original surface and the velocity depending on Q the volume removal rate and also depending on the interfacial area of both electrodes. So, obviously, if we consider a 1-dimensional motion the volume removal rate per unit area of interface of the electrode would be nothing but the velocity of the recission of the surface because of the dissolution.

So, therefore, we can easily say that dy by dt which where as you have already seen before y is really is this distance. So, distance between the workpiece and the tool at a function of time. So, dy by dt becomes equal to the dissolution which is A I by rho Z F per unit area.

Let us say the area in this particular case is q some small q. So, this is the interfacial area. So, that is how the surface is receding and this recission is in the opposite direction as the feed. Remember as we were talking about the 2 electrodes here, this is the work this right here is the electrode or the tool. So, work is being fed in this direction minus y direction and the recission of the workpiece surface is in the plus y direction because of the dissolution. So, recission is given by this term A I by rho Z F per unit area, area of this shaded area is the shaded area the interfacial area of the 2 surfaces.



So, f is basically the feed. So, this minus the feed is the total amount you know still kind of going backward which is the change of this y with respect to time dy by dt. So, I by q is current density vector J. So, A J by rho Z F minus f is how this formulation will look like and of course, we have already found out what this J value would be. So, we can say that dy by dt equal to A J by rho Z F minus f can be written down as k A times of v minus delta V divided by rho Z F where this k V minus delta V by y is the current density vector minus f.

If you pull out y of the whole term it happens to be some constant 1 by y minus f. Let us call this lambda. So, we have dy by dt is equal to lambda by y minus f and this is actually the kinematic equation for an ECM process. So, we will investigate various cases of constant feeds or zero feeds in the next lecture. Today we are sort of coming towards the end of this particular lecture. So, we will in a nutshell try to investigate how this y varies particularly when the feed is constant, when the feed is zero feed, or you know something where there is a definition of equilibrium gap which comes between this receding surface and the feed when they equalise each other. So, we will look at those details in the next lecture. Thank you.