

Ordinary Differential Equations (noc 24 ma 78)

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Week-04

Lecture-17 : Fundamental theorem of linear Systems

Hello students, in this video we are going to talk about fundamental theorem of linear systems. Sorry, let me write it properly. Fundamental theorem for linear systems. Systems. So, essentially, you see, we talked about the linear system, right, variable coefficient.

So, we know that if we are looking at this problem, x' equals to A times x , okay, x at the point 0 is x_0 , then the problem has a unique solution, problem admits an unique solution, admits an unique solution. unique solution and how is the, what is the solution here? It is given by x of t is the fundamental matrix ϕ of t times a constant which is a n cross 1 constant, okay, sorry, this initial data is given, right, so it is nothing but ϕ inverse of 0 times x_0 , right, ϕ is the fundamental matrix, the fundamental matrix. fundamental matrix okay now the point is this this is okay but the thing is for real life calculations it is not a very feasible option so what we do is this and this is why we talked about matrix exponential in the first place in the last video okay so what we do is this see let us say so as a motivation let us look at some motivation motivation.

So, let us look at this problem. See, x' equals to Ax , let us say, yeah, and x_0 equals to x_0 , yeah. You can easily check that x equals to x_0 times e^{At} , okay, is a solution, is the only solution, is the only solution, right, only solution. A is in \mathbb{R} , right, A is in \mathbb{R} given, Okay.

x is the only solution. Now the thing is this from here we can actually motivate ourselves that what should be. So now the question is can one find similar results for x' equals to x at the point 0 is x_0 okay i am writing 0 you can take it to be t_0 no problem okay now here you see please remember remark what i what i am going to do now okay whatever follows whatever follows in this video in this video is only valid for a constant coefficient system.

Constant coefficient system. Clear? Okay. See, this thing, this actually holds for fundamental matrix solution. That actually holds for variable coefficient.

No issue there. But the thing is, we can actually, we expect that, let us say, the variable coefficient becomes a constant coefficient. We can actually say more, right? Okay. We can see much more details.

So, that is what we are trying to do here. So, let us say you have a constant coefficient problem, $x' = Ax$, $x(0) = x_0$. Let us call that as star. We want to find the solution. Okay.

From the earlier thing, motivation, we can say that this is the thing M . You see, you can actually see, I mean, you can think of it like this, that e^{At} times x_0 should solve star. You see, here, e^{At} times x_0 is a solution of this problem, right? Now, if you are making it a way an $n \times n$ system, then that for that system e^{At} times x_0 has to be the solution. You have to write it like this because e^{At} is a $n \times n$ matrix and this is a $n \times 1$ vector, right?

So, then make sense. You cannot write x_0 times e^{At} . Please remember that. You cannot write x_0 times e^{AT} , yeah? Okay.

So, please remember this part. clear now you see the thing is $x(t) = e^{At} x_0$ should be the solution right that's what we can expect from this particular thing okay so we are going to do that part okay right so this is the main aim however okay so let's look at a lemma first lemma let A be a $n \times n$ matrix. B be a $n \times n$ matrix. Then we want to talk about the derivative of e^{At} .

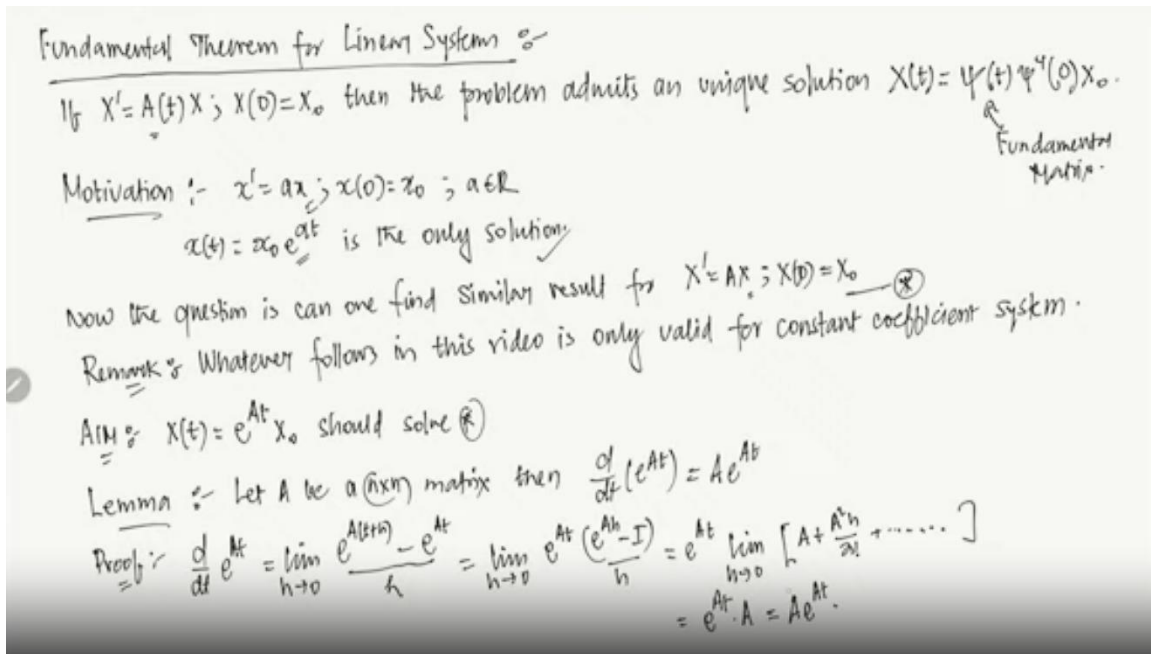
Then $\frac{d}{dt} e^{At}$. What happens here? Okay, now from one variable you do realize it should be, this should look like this. e^{At} , e^{AT} . It should look like this.

Yes, and actually it does. Okay, so you do not have to worry about it. Okay, but the thing is we of course need a proof of that. So let us look at a proof. Proof.

So, $\frac{d}{dt} e^{At}$ is nothing but this is our usual definition $\lim_{h \rightarrow 0} \frac{e^{A(t+h)} - e^{At}}{h}$. So, this is nothing but $\lim_{h \rightarrow 0} \frac{e^{At} e^{Ah} - e^{At}}{h}$ okay $e^{At} \lim_{h \rightarrow 0} \frac{e^{Ah} - I}{h}$ you can write it like this right by h clear so this is nothing but $e^{At} \lim_{h \rightarrow 0} \frac{e^{Ah} - I}{h}$ i can take the e^{At} outside because it does not depends on h so $\lim_{h \rightarrow 0} \frac{e^{Ah} - I}{h}$ what is e^{Ah} it is nothing but $I + Ah + \frac{A^2 h^2}{2!} + \dots$ so $\frac{Ah}{h}$ it will get cancelled

I am now moving this thing okay okay okay now this is nothing but what happens this is nothing but e power a t times a right, okay, which is again, I mean, this, this actually you can see that this actually commutes, so you can write it as A e power At, clear. So, we have our, so, you know, result, okay.

See, the last equality which we are doing, so basically e power AT converges uniformly, okay, so that is why you can change the, you know, the two limits essentially, okay. fine um i did miss something no i have missed something limit h tensors below what is the k okay fine yeah this okay so right.



So, now we talk about the fundamental theorem. Okay. So, theorem. So, let A be a n cross n matrix. n cross n matrix. Okay. Then given a x 0 in Rn. okay. The initial value problem, the initial value problem x prime equals to x, x0 equals to x0. So, please remember this is a constant coefficient, okay. Admits an unique solution, unique solution. What is the unique solution? Given by

given by x of t is e power a t times x1, okay? This is what you see. We were expecting this, right? So, this theorem actually says that you have a unique solution. Unique solution is guaranteed by Picard's existence and uniqueness.

And you actually say that there is a unique solution which is given like this, yeah? Okay. So, how do you prove something like this? See proof. if x t is nothing but e power a t times x 0, okay, that will imply x prime of t is d dt of e power a t times x 0, okay.

See, x_0 does not, it does not independent of t , right. So, we can, and so d/dt of e^{at} is $a e^{at}$, we know that it is $a e^{at}$ times x_0 . So, you see and e^{at} times x_0 is nothing but x_t . So, this is a times x of t . So, x' equals to a times x of t . So, x_t satisfies the equation for all t in \mathbb{R} . So, x_t given by e^{at} times x_0 satisfies the equation for all t in \mathbb{R} . Also, x of 0 is nothing but identity times x_0 which is identity times x_0 which is nothing but x naught right okay so therefore okay see the thing is we have to show

that see what we showed is x_t equals to e^{at} times x_0 satisfy the equation yes now the thing is this how do you show this is the only solution of course you can use directly Picard's theorem and you can say that this is has to be the only solution there is no other way without Picard's theorem also you can prove let's just look at that proof okay so what you do is you define Define y of t to be e^{-at} times x_t . You see similar sort of thing we did it in the last video also if you remember. y of t equals to e^{-at} times x_t . Then what is y' of t ? y' of t is nothing but $-a$ times e^{-at} times x_t plus e^{-at} times x'_t . So, this is nothing but $-a$ times x of t plus e^{-at} times x' of t and what is x' of t ?

It is nothing but a times x . So, $-a$ times e^{-at} times x_t plus a times e^{-at} times x_t . Now, $-a$ and a times e^{-at} times x_t , they actually commutes. Okay. So, these two commutes, this one and this one commutes with each other. So, basically, we can write this is essentially 0 .

Right. That will imply y of t is nothing but constant. Okay. y of t is constant. And what is y at the point 0 ?

This is nothing but x of 0 , which is x_0 . Okay. So, if this is x_0 , then what happens is that will imply y of t is always x_0 , right? x naught for all t in \mathbb{R} . And then we can actually say what is y of t ? It is x of t then is nothing but e^{at} times x_0 .

So this is proved. So this holds for all t in \mathbb{R} . Now so what we understood here is this. See if you have a constant coefficient equation at least homogeneous constant coefficient equation what we have is you have a unique solution given by e^{at} times x_0 and that solution is valid for all of \mathbb{R} . All of \mathbb{R} .

Theorem :- Let A be a $(n \times n)$ matrix. then given $X_0 \in \mathbb{R}^n$, the I.V.P

$$X' = AX; X(0) = X_0$$

admits an unique solution given by $X(t) = e^{At} X_0$.

Proof :- If $X(t) = e^{At} X_0 \Rightarrow X'(t) = \frac{d}{dt} (e^{At} X_0) = A e^{At} X_0 = AX(t) \quad \forall t \in \mathbb{R}$

Also, $X(0) = I \cdot X_0 = X_0$

\therefore Define, $Y(t) = e^{-At} X(t)$

$$\therefore Y'(t) = -A e^{-At} X(t) + e^{-At} X'(t)$$

$$= -A e^{-At} X(t) + e^{-At} A X(t) = 0$$

$\therefore Y(t) = \text{constant}$ and, $Y(0) = X_0 \Rightarrow Y(t) = X_0 \quad \forall t \in \mathbb{R}$
 $\Rightarrow X(t) = e^{At} X_0 \quad \forall t \in \mathbb{R}$ □

See the thing is here you may ask Why don't we use Picard? You can use Picard for the uniqueness thing. But the thing is that is not guaranteeing that you can have a solution for all t . It only guarantees in a small neighborhood of 0. But here you can actually using this proof you can actually say this works for all t . So let us look at a simple example. So let us say that We have this problem, x' prime equals to minus 2, minus 1, 1, minus $2x$, okay? And x at the point 0 is a vector given by 1 and 0.

Okay, now I want to find out what the solution is. So, the solution x of t , what do we know? We know this is a t times x_0 . Okay, so you just have to calculate e power a t and you are done. Okay, and what is e power a t ?

You see this is in this form. If you remember, we did one problem, right? This problem, you see a minus b , b , a . Yes, in this form, e power a we calculated, which is looks like e power a cosine b minus sine b , sine b cosine b . Okay, so we can use this property here. So, since e power a t , what is e power a t ? Let us just write it down.

I am just writing it directly. I am not calculating anything, writing it directly. Cosine t minus sine t , sine t and cosine of Clear? Okay.

So, you just put this vector here and acting at 1, 0. So, the answer which you are going to get, I am not calculating again. You can calculate it yourself. So, you have to check it yourself. It is cosine t and sine t. Okay.

So, please check it yourself. Clear? Okay. So, this is how you calculate this. Very, very simple.

Okay. Now, the thing is this. If I, the question is, which I want to pose is this question. Okay. You see, x' equals to Ax , $x(0)$ equals to x_0 has a unique solution in terms of fundamental matrix, right?

Solution in terms of fundamental matrix given by, given by $\Phi(t)$, which is $\Phi(t)$, fundamental matrix $\Phi(t)$, $\Phi^{-1}(0)$ times x_0 , right? That we know, okay? So, Φ is a fundamental matrix, fundamental matrix, okay? And you can show that this holds for all t in \mathbb{R} ,

Okay. Now, the thing is, but again, this theorem says that x' equals to Ax , $x(0)$ equals to x_0 has, you know, this unique solution e^{At} times x_0 . Okay. So, is there a relation? So, is there a relation of the fundamental matrix, fundamental matrix

matrix Φ of A with exponential of A . What do you think? See, the thing is, you have to understand that in both the situations, it is a unique solution, exactly same equation and it passes through the same vector x_0 in \mathbb{R}^n , right? So, therefore, one can say that without, you know, putting much emphasis here, $\Phi(t)\Phi^{-1}(0)$ has to be e^{At} , no? It has to be e^{At} .

There is no other option here, okay? So, you see, if there is, so this is another way of, I mean, calculating e^{At} if you want, okay? So, if one can calculate, okay, We will explore all these things in the future videos. But for now, this is just for information.

If one can calculate fundamental matrix or if it is given, let us say, the fundamental matrix, then calculating exponential is easy. Calculating exponential is easy. Exponential of a matrix is easy. is easy. Now, you have to understand, please remember this thing.

This actually holds only when it is constant coefficient. Variable coefficient equation, you can of course write it in terms of fundamental matrix, the solution, but you cannot have this thing. So, $\Phi(t)\Phi^{-1}(0)$ is nothing but e^{At} . So, with this, I am going to end this video.

$$\text{Ex: } X' = \begin{pmatrix} -2 & -1 \\ 1 & -2 \end{pmatrix} X ; X(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$X(t) = e^{At} X_0 = e^{-2t} \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} \quad (\text{Check it yourself}).$$

$$\left[\because e^{At} = e^{-2t} \begin{pmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{pmatrix} \right]$$

Question: $X' = AX ; X(0) = X_0$ has a unique solution given by $X(t) = \underbrace{\Psi(t)\Psi^{-1}(0)}_{\text{Fundamental Matrix}} X_0, \forall t \in \mathbb{R}.$

So, is there a relation of the Fundamental Matrix of A with e^A .

$$\therefore \underline{\Psi(t)\Psi^{-1}(0) = e^{At}}.$$

So, if one can calculate F.M then calculating exponential of a matrix is easy.