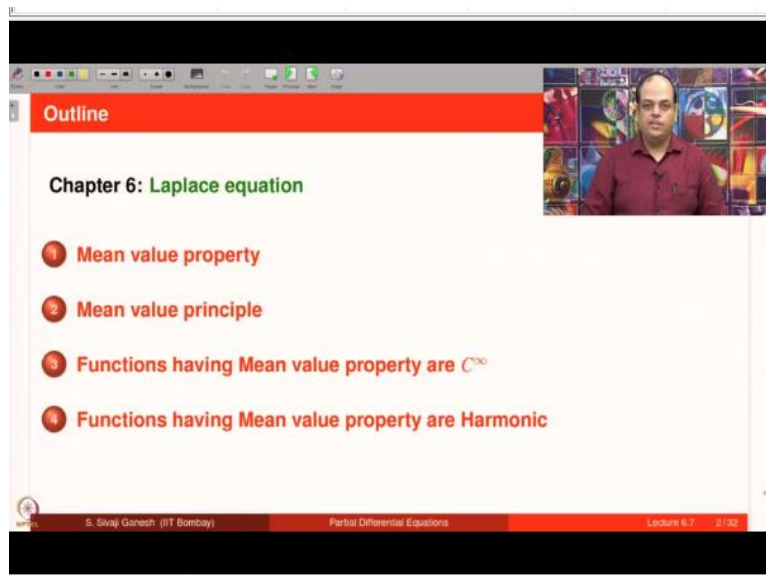


Partial Differential Equations
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Lecture-51
Laplace Equation
Mean Value Property

Welcome, in this lecture, we are going to discuss about mean value property and some of its consequences.

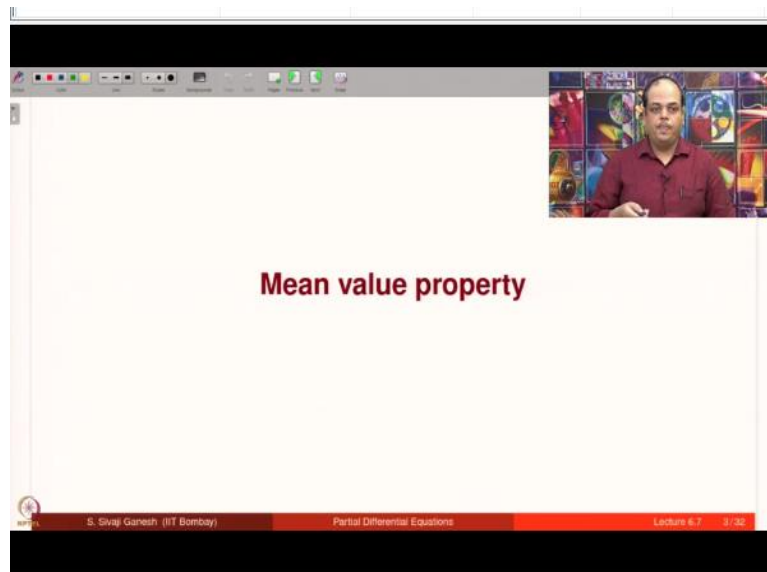
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The outline of this lecture is as follows. First we introduce what is called mean value property. And then we go on to show mean value principle namely mean value property holds for harmonic functions, that is what is called mean value principle. Then we show that functions having mean value property are C^∞ functions and functions having mean value property are harmonic functions.

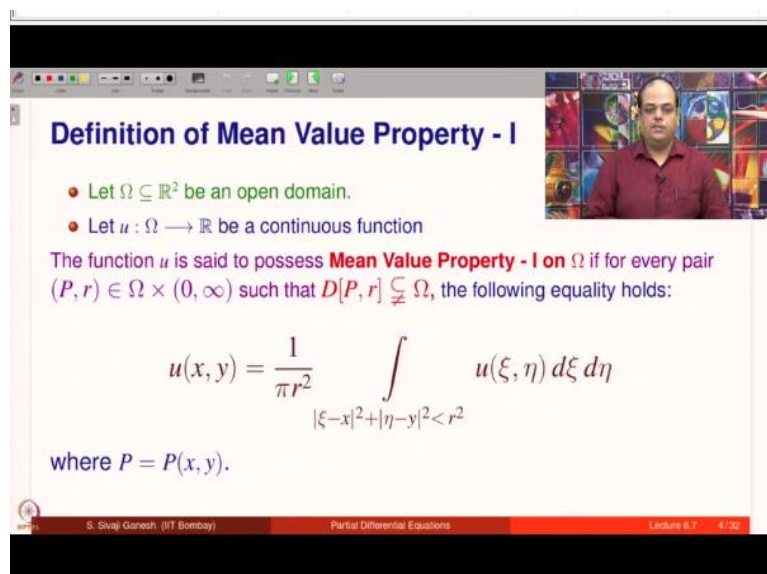
In 3 and 4 points here, we are going to assume only continuity of the function. A continuous function has mean well property automatically it follows C^∞ ; if a continuous function has mean well property then it is automatically a harmonic function.

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So, what is mean value property?

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So, we are going to define 2 notions of mean value property that they are called mean value the property I and mean value property II. First let us define what is mean value property I? Let Ω instead \mathbb{R}^2 to be an open domain, let u from Ω to \mathbb{R} be a continuous function. The function u is said to possess mean value property I on Ω if for every pair P, r such that the close disk of radius r with center at D is properly contained in Ω . What does this mean? Take any point in Ω and take any r positive such that this close disk is contained in Ω .

Then the following equality holds, u of x, y , x, y is P, P of x, y , P is P of x, y . So, u of x, y equal to integral of u over the disk $D[P, r]$ and this is πr^2 is precisely the area of the

disk. That means, I am integrating the function on this domain $D(P, r)$ and dividing it with the area of $D(P, r)$. Therefore, this is called mean value. So, $u(x, y)$ is nothing but you take a disk around x, y which is this $D(P, r)$ integrate and divide with 1 by πr^2 . In other words, the value of u at the center of a disk is given by its average on the disk.

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Definition of Mean Value Property - II

- Let $\Omega \subseteq \mathbb{R}^2$ be an open domain.
- Let $u : \Omega \rightarrow \mathbb{R}$ be a continuous function

The function u is said to possess **Mean Value Property - II** on Ω if for every pair $(P, r) \in \Omega \times (0, \infty)$ such that $D[P, r] \subseteq \Omega$, the following equality holds:

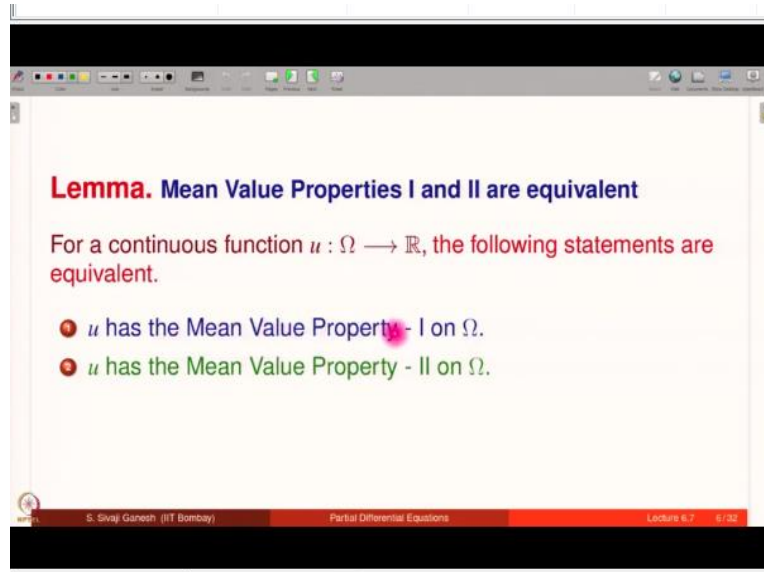
$$u(x, y) = \frac{1}{2\pi r} \int_{S(P, r)} u(s) ds$$

where $S(P, r)$ denotes the circle centered at $P(x, y)$ having radius r .

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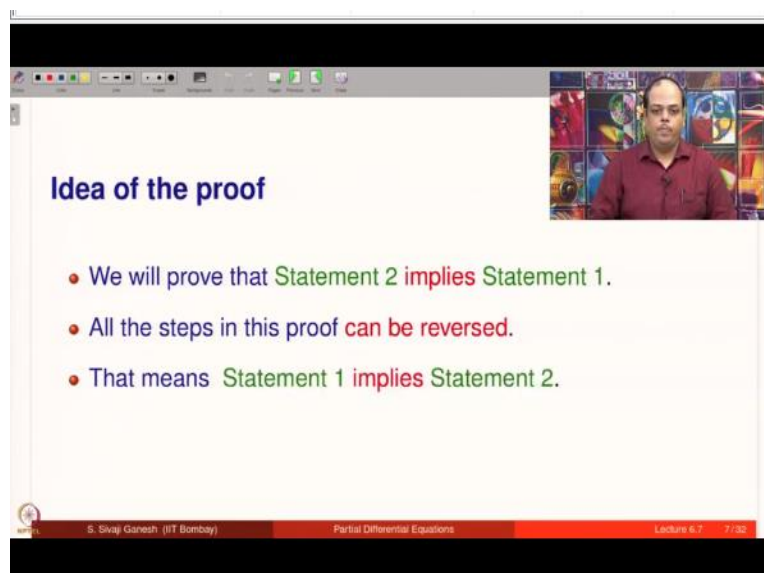
Definition of mean value property II: Let Ω be once again an open domain in \mathbb{R}^2 and let u be a continuous function on Ω . Then the function is said to possess mean value property II if for every point P in Ω and for every r positive such that this closed disk is contained in Ω something should happen. What would happen is $u(x, y)$ is nothing but integrate u over the circle $S(P, r)$ denotes a circle centered at P having radius r and divided with perimeter of a circle. In other words, this is the mean value of u on the circle is equal to the value of u at the center of the circle. So, this is called mean value property II.

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So, we have a result which says that mean value properties I and II are equivalent, what does that mean? If you have a continuous function u on Ω , then the following statements are equivalent, u has a mean value property I on Ω is same as u has a mean value property II on Ω . So, this means that if you have a continuous function and it has the mean value property I then automatically it has mean value property II. Similarly, if the function u has a mean value property II on Ω then definitely will also have the mean value property I on Ω .

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So, what is the idea of the proof? We are going to prove the statement 2 implies statement 1. All the steps in this proof can be reversed. That means statement 1 implies statement 2.

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Proof of (2) \implies (1)

Let $P(x, y) \in \Omega$ be an arbitrary point. Further let $r > 0$ be such that $D[P, r] \subseteq \Omega$.

If u has the **Mean Value Property - II**, then for every $0 < \tau \leq r$ we have

$$u(x, y) = \frac{1}{2\pi} \int_0^{2\pi} u(x + \tau \cos \theta, y + \tau \sin \theta) d\theta.$$

Multiply the last equation with τ and then integrate w.r.t. τ over the interval $[0, r]$.
This yields

$$\int_0^r \tau u(x, y) d\tau = \frac{1}{2\pi} \int_0^r \left(\int_0^{2\pi} u(x + \tau \cos \theta, y + \tau \sin \theta) d\theta \right) \tau d\tau.$$

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So, let us prove 2 implies 1. So, let P be an arbitrary point in Ω . Further let r positive be such that the closed disk with center P radius r is inside Ω . If you have the mean value property II then for every τ less than or equal to r we have this equality. This is a mean on the circle equal to u at the center. Now, of course, by the definition it holds for r , why does it hold for every τ less than or equal to r ?

It is because if D of P , r is in Ω then D of P τ will also be a subset of Ω . For every τ less than or equal to r therefore, this holds for every τ less than or equal to r . Now, multiply the last equation with τ and then integrate with respect to τ over the interval 0 to r . So, I have simply multiply this equation with τ and wrote this integral 0 to r on both sides.

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Proof of (2) \implies (1) (contd.)

The equation

$$\int_0^r \tau u(x, y) d\tau = \frac{1}{2\pi} \int_0^r \left(\int_0^{2\pi} u(x + \tau \cos \theta, y + \tau \sin \theta) d\theta \right) \tau d\tau$$

simplifies to

$$\begin{aligned} \frac{r^2}{2} u(x, y) &= \frac{1}{2\pi} \int_0^r \int_0^{2\pi} u(x + \tau \cos \theta, y + \tau \sin \theta) \tau d\theta d\tau \\ &= \frac{1}{2\pi} \int_{|\xi-x|^2+|\eta-y|^2 < r^2} u(\xi, \eta) d\xi d\eta. \end{aligned}$$

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Now, we can integrate the left hand side because u of x, y does not depend on τ . So, it is a constant. So, integral 0 to r of $\tau d\tau$ that will give us τ^2 by 2 with limits 0 to r . So, that gives us r^2 by 2 into u of x, y . Right hand side I have written as it is. Now, what is right hand side? It is nothing but the integral on the disk expressed in the polar coordinates. In polar coordinates $\tau d\theta d\tau$ is the area element. And therefore, this integral is equal to this integral. Now, from here, you get what is u of x, y because you bring r^2 by to this side you get 2 by r^2 then you get 1 by πr^2 into integral u on the disk.

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Proof of (2) \implies (1) (contd.)

Thus we get

$$u(x, y) = \frac{1}{\pi r^2} \int_{|\xi-x|^2+|\eta-y|^2 < r^2} u(\xi, \eta) d\xi d\eta,$$

which proves that u has Mean Value Property - I as well.

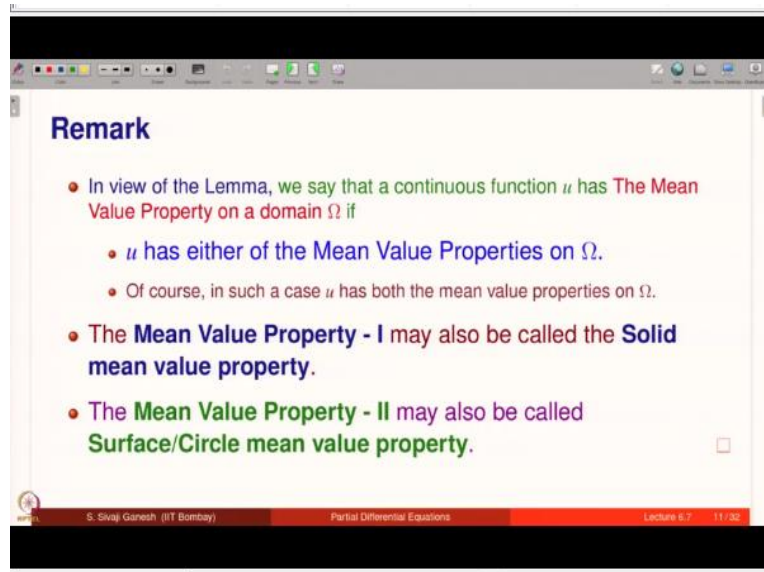
How to retrace the steps

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So, that finishes the proof of mean value property I. Now, how to retrace the steps and prove 1 implies 2. Let us do that. This is what we have; this is what we assume. If you have mean value property I we have this equation that is on multiplying with r^2 by 2. We have r^2 by 2 x, y equal to this. Now, we can express this as this integral in the polar coordinates. Now, I want to pass from this equation to this equation; what do I do?

Right hand side is the same, left hand side is precisely this is nothing but this integral. So, we have got this. That means, we have this last equation on the slide. Now, from here to I want to pass to this; how do I do that? Apply fundamental theorem of calculus then 0 to r will go away and what you will have is r times u of x, y and here 1 by 2π 0 to 2π and τ replaced by r then we will have this then cancel r u of this. So, therefore, we can retrace the steps and through that 1 implies 2.

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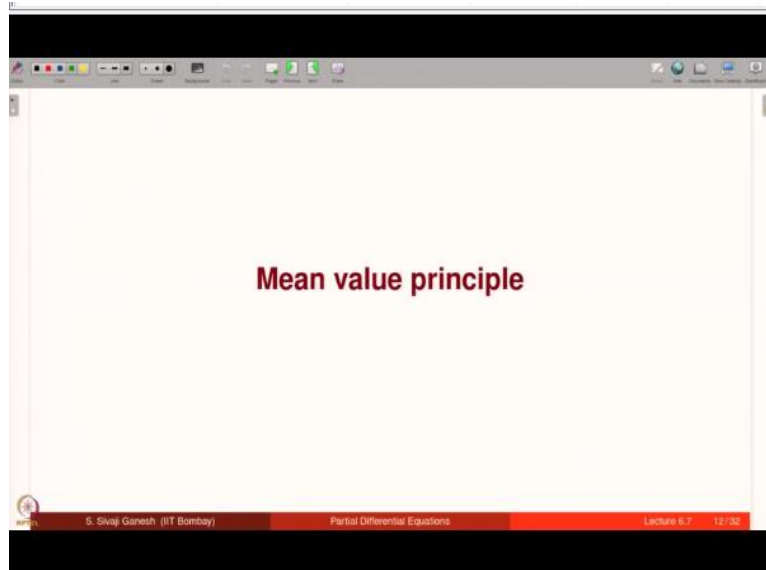


Remark; in view of this lemma that we have just proved we say that a continuous function has the mean value property on a domain Ω , we do not mention which one. If u have either of the mean value properties I am going to say that the function u has the mean value property, we need not mention which one of them because they are equivalent. Of course, in such a case you have both the mean value properties.

If it has one mean value property, it has both the mean value properties. That is the reason we would not mention which one. So, the mean value property I may also be called the solid mean value property. This because in mean value the property I features mean on the disk that means I am integrating the entire disk and taking the average. That is why it is called solid mean value property.

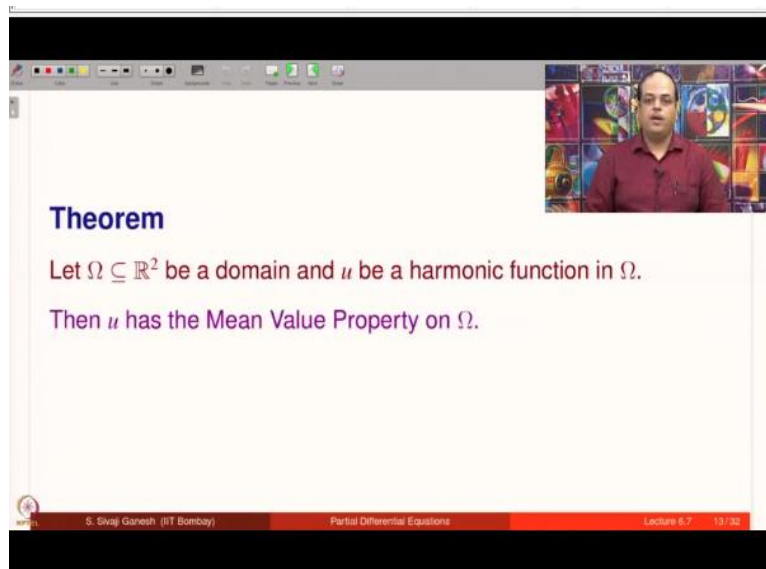
And the mean value property II may be called as a surface or circle mean value property. This terminology is not very standard I am using this terminology because we can easily understand by names. Names represent a quantity much more than a very generic name like mean value property I, II, III etcetera. Solid mean value property means I understand it, how to write it. Similarly surface mean value property I know what does it mean I can easily recall.

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Let us prove now mean value principle.

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Select ω be a domain in \mathbb{R}^2 and u be a harmonic function on ω . Then u has the mean value property on ω .

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Proof of Theorem

We plan to show that u has **Surface Mean Value Property**

Let $P_0(x_0, y_0) \in \Omega$ be arbitrary and let $R > 0$ be such that

$$D(P_0, R) \subset D[P_0, R] \subset \Omega.$$

We need to prove

$$u(x_0, y_0) = \frac{1}{2\pi} \int_0^{2\pi} u(x_0 + R \cos \theta, y_0 + R \sin \theta) d\theta.$$

If u has to have **Mean Value Property**, then the above equation should hold for every $0 < r < R$. **This observation shows us a way forward to the proof.**

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So, proof of the theorem. We plan to show that u has a surface mean value property. So, if you want to show that u has mean value property I can choose to prove any one of them which is convenient. I am going to show that u has surface mean value property. Select P_0 be a point x_0, y_0 in Ω be arbitrary, unlike capital R be such that this open disk is contained the closed that is contained in Ω .

And we need to prove that u at the center of the disk is given by the average of u on the circle. If u has to have mean value property then the above equation namely this should hold when I replaced this capital R with any r which is less than R . This observation shows us a way how to proceed forward.

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Proof of Theorem (contd.)

Thus we expect that for $0 < r < R$, the equality

$$u(x_0, y_0) = \frac{1}{2\pi} \int_0^{2\pi} u(x_0 + r \cos \theta, y_0 + r \sin \theta) d\theta.$$

will hold.

In the above equation, the LHS is a real number while RHS depends on r .

Thus the strategy is to prove that the RHS is a constant function of the variable r .

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So, that we expect that for r between 0 and R this equality will hold. In the above equation, the LHS is a real number u at the point x_0, y_0 is a number. Whereas, the right hand side is a function of r , it depends on r . Therefore, the strategy is show that the right hand side is a constant function of the variable r .

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Proof of Theorem (contd.)

Define a function $V : (0, R) \rightarrow \mathbb{R}$ by

$$V(r) := \frac{1}{2\pi} \int_0^{2\pi} u(x_0 + r \cos \theta, y_0 + r \sin \theta) d\theta.$$

Suppose we show that $\frac{dV}{dr} = 0$ for $0 < r < R$.

As a consequence, for every r we would have for every $0 < r < R$

$$V(r) = \lim_{\rho \rightarrow 0} V(\rho) = u(x_0, y_0),$$

which completes the proof of theorem as $V(r)$ would then equal $u(x_0, y_0)$.

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So, therefore, define a function V on this interval $0, R$ by this formula, which is precisely the right hand side on the last equation in the previous slide. Suppose, we show that dV by $dr = 0$ what does it mean? V is the constant function on this interval $0, r$. So, as a consequence for every r in interval $0 R$ we get that V of r is constant, but what is that? That constant can be evaluated by taking limit ρ goes to 0 of V of ρ .

And that will be u of x_0, y_0 . On the other side is a constant V is a continuous function of r therefore, V of r is also equal to limit ρ goes to R of V of ρ and that will give you V of R which is precisely the right hand side in the circuit mean value property. So, this completes the proof. As V of $r = u$ of x_0, y_0 .

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Proof of Theorem (contd.)

It remains to show that $\frac{dV}{dr} = 0$ for $0 < r < R$.

$$\begin{aligned} \frac{dV}{dr}(r) &= \frac{1}{2\pi} \int_0^{2\pi} \frac{\partial}{\partial r} u(x_0 + r \cos \theta, y_0 + r \sin \theta) d\theta \\ &= \int_{S(P_0, r)} \partial_\nu u \, d\sigma \\ &= \int_{D(P_0, r)} \Delta u \, dx = 0. \end{aligned}$$

Note that Green's identity - I and harmonicity of u on Ω

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So, it remains to show that this derivative of V with respect to r is 0, let us compute. So, dV by dr is given by this. I have taken the differentiation inside the integral. That is allowed because u is a smooth function you just see the function and this is precisely this, this is the normal derivative of u on the boundary that is normal derivative of u on the circle. Now, this is nothing but integral over the disk of Laplacian $u \, dx$ and that is 0 because u is a harmonic function. So, we have used Green's identity I in passing from this to this and harmonicity of u in contributing that this integral is 0 because the integrand is 0.

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A continuous function having mean value property is infinitely differentiable

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So, if you have a continuous function which has mean value property it is infinitely differentiable.

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Theorem

Let u be a continuous function on Ω .
 Further, let u have the Mean Value Property on Ω .

Then

- 1 u has continuous derivatives of all orders on Ω .
- 2 All the derivatives of u have the Mean Value Property on Ω .

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So, let u be a continuous function on Ω . Ω is a subset of \mathbb{R}^2 . Let u have the mean value property on Ω then u has continuous derivatives of all orders on Ω and all the derivatives of u have the mean value property on Ω . So, point 1 says use (1) (13:27) function and this says all the derivatives have a mean value property on Ω .

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Proof of Theorem

Step 1

- It is sufficient to show that the first order partial derivatives of u exist and are continuous.
- Once it is known that first order partial derivatives of u exist and are continuous, we can compute partial derivatives from the equation

$$u(x, y) = \frac{1}{2\pi} \int_0^{2\pi} u(x + r \cos \theta, y + r \sin \theta) d\theta$$

- Note that the above equation holds for r s.t. $D(P, r) \subset \Omega$ as u satisfies mean value property on Ω , where $P(x, y) \in \Omega$ is arbitrary.

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Step 1 it is sufficient to show that the first order partial derivative of u exists and are continuous. Once it is known that first order partial derivative of u exists under continuous, we can compute partial derivatives from this equation. This is known to hold because u has the mean value property. So, this holds. The question is whether I can differentiate this? I can if I know that the integrand is differentiable, that is what we are establishing that first order partial derivatives of u exists under continuous.

Therefore, differentiating this equation is allowed. Note that the above equation holds for all r such that this closed disk with center at P is inside ω as you satisfies mean value property on ω where P is an arbitrary point in ω . Mean value property holds on ω means, you take any closed disk which is contained in the domain ω then mean value property that is u at the center of the disk is given by the average. Let it be solid average or the surface average.

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Proof of Theorem (contd.)
Step 1 (contd.)
 The partial derivatives satisfy

$$u_x(x, y) = \frac{1}{2\pi} \int_0^{2\pi} u_x(x + r \cos \theta, y + r \sin \theta) d\theta,$$

$$u_y(x, y) = \frac{1}{2\pi} \int_0^{2\pi} u_y(x + r \cos \theta, y + r \sin \theta) d\theta.$$

The above equations mean that u_x, u_y have the mean value property.

Repeating the arguments by replacing u with its partial derivatives, we conclude that u has partial derivatives of all orders and all of them satisfy the mean value relation.

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So, the partial derivatives satisfy u_x of x, y equal to this are differentiated with respect to x and similarly u_y . The above equations mean that u_x, u_y have the mean value property, because that this is exactly means that u_x has the mean value property. Repeating the arguments by replacing u with its partial derivatives, we conclude that u has partial derivatives of higher orders and all of them satisfy the mean value property.

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Proof of Theorem (contd.)
Step 2: Existence of 1st order derivatives of u and their continuity

Since u has Mean Value Property - I, we have

$$u(x, y) = \frac{1}{\pi r^2} \int_{|\xi-x|^2+|\eta-y|^2 < r^2} u(\xi, \eta) d\xi d\eta.$$

Writing the double integral on the RHS as iterated integrals, we get

$$u(x, y) = \frac{1}{\pi r^2} \int_{y-r}^{y+r} d\eta \int_{x-\sqrt{r^2-(\eta-y)^2}}^{x+\sqrt{r^2-(\eta-y)^2}} u(\xi, \eta) d\xi$$

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Now, let us show that first order derivatives in fact exist and are continuous. Since you have the mean value property, it has a mean value property I also therefore we have this expression for u at the center of this disk. Now, writing the double this integral on the disk, write it as iterated integrals, we get u of x, y equal to so this integral is precisely this integral.

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Proof of Theorem (contd.)
Step 2 (contd.)

The equation

$$u(x, y) = \frac{1}{\pi r^2} \int_{y-r}^{y+r} d\eta \int_{x-\sqrt{r^2-(\eta-y)^2}}^{x+\sqrt{r^2-(\eta-y)^2}} u(\xi, \eta) d\xi$$

tells us that $u_x(x, y)$ exists, in view of fundamental theorem of integral calculus.

In fact $u_x(x, y)$ is given by

$$u_x(x, y) = \frac{1}{\pi r^2} \int_{y-r}^{y+r} \left[u(x + \sqrt{r^2 - (\eta - y)^2}, \eta) - u(x - \sqrt{r^2 - (\eta - y)^2}, \eta) \right] d\eta.$$

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So, this equation tells us that u_x of x, y exists how? x is appearing here inside and this integrand, imagine this is the first integral then it has an integrand which is this, there the dependence on the x is only through the limits and it is a nice dependence. So, by fundamental theorem of calculus this is differentiable and we can compute. So, when you compute and you differentiate this with respect to x you get this particular integrand here.

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Proof of Theorem (contd.)
Step 2 (contd.)
 Since the RHS of the equation

$$u_x(x, y) = \frac{1}{\pi r^2} \int_{y-r}^{y+r} \left[u(x + \sqrt{r^2 - (\eta - y)^2}, \eta) - u(x - \sqrt{r^2 - (\eta - y)^2}, \eta) \right] d\eta.$$

is a continuous function of (x, y) , we conclude that u_x is a continuous function on Ω .

Similarly one can deduce the existence of u_y at each point and continuity of u_y on Ω . \square

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So, since the right hand side of this equation that is this is continuous function of x, y , it follows that u_x is a continuous function of x, y . So, thus we are shown that u have a partial derivative with respect to x and u_x is continuous function. Similarly, one can deduce the existence of u_y at each point and the continuity of u_y on Ω .

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**A continuous function having mean value property
 is harmonic**

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A continuous function having mean value property is indeed harmonic.

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Theorem

Let u be a continuous function on Ω .
 Further, let u have the Mean Value Property on Ω .

Then u is harmonic in Ω .

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So, let u be a continuous function on Ω . Assume that you also has a mean value property on Ω then u is harmonic in Ω . It means Laplacian $u = 0$ holds on Ω .

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Proof of Theorem

- **Proved earlier:** If u has the mean value property, then all partial derivatives of u exist and all of them are continuous on Ω .
- We want to show that $\Delta u = 0$.
- On the contrary, suppose that there exists a point $P_0(x_0, y_0) \in \Omega$ such that $\Delta u(P_0) \neq 0$. **WLOG** assume that $\Delta u(P_0) > 0$.
- By continuity of the 2nd order derivatives, there exists a disk $D(P_0, \epsilon)$ which is centered at P_0 and having radius $\epsilon > 0$ on which $\Delta u > 0$.

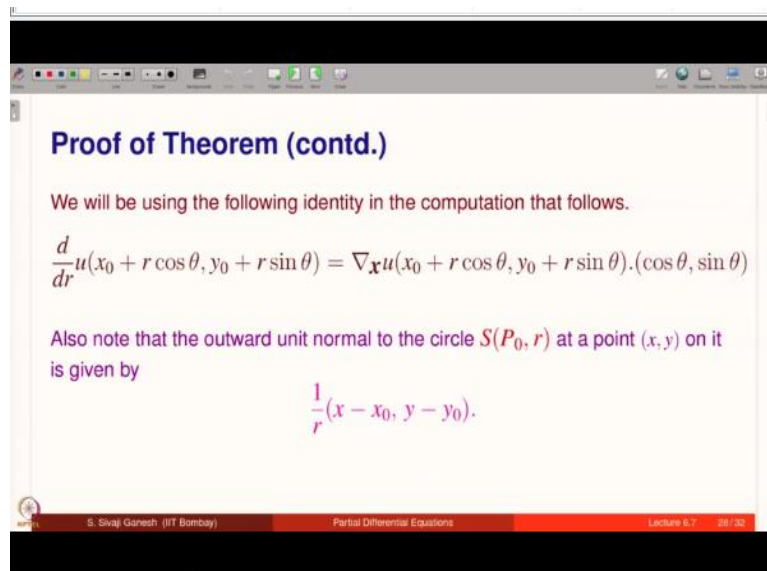
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So, proof of the theorem, we have proved this earlier, if u is a continuous function and has a mean value property then all partial derivatives of u exists and all of them are continuous on Ω ; we have shown this. So, we want to show that Laplacian = 0 therefore, why we stated this is because Laplacian u should be meaningful, because we have only started with a continuous function.

So, as shown before u has all derivatives in particular secondary derivatives, therefore, Laplacian u is meaningful and we can think of showing that to be equal to 0. So, on the contrary assume that Laplacian u is not equal to 0 in Ω that means there is a point P_0 in

omega, where Laplacian u is not 0. Now, Laplacian u is a combination of second order partial derivatives of u, which are known to be continuous on omega. So, you have a continuous function namely Laplacian u, which is not 0 at a point P 0 therefore, in a disk around P 0 it will continue to be non-zero.

Without loss of generality, let us assume Laplacian u of P 0 is positive. What are the choices for Laplacian u of P 0 when it is non-zero it has to be positive or negative? So, let us assume it is positive, if it is negative exactly the same proof we can rewrite. Let us go ahead with Laplacian of u of P 0 as positive. By continuity of the second order derivatives, there is a disk D of positive radius epsilon centered at P 0 such that Laplacian u is greater than 0 on the disk. **(Refer Slide Time: 18:52)**



So, we will be using the following identity in the computation that follows $\frac{d}{dr} u$ of this quantity. By chain rule it is a gradient of u and then dot product with the derivative of the inside quantity with respect to r namely cos theta, sine theta. Also note that the outward unit normal to the circle at any point on it is given by $\frac{1}{r}(x - x_0, y - y_0)$. If you recall we have said this earlier as $\frac{\partial u}{\partial \nu}$ at a point on the boundary of the domain. That is at a point on the circle, this is the $\frac{\partial u}{\partial \nu}$ because this is a normal direction or the unit circle.

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Proof of Theorem (contd.)

For $0 < r < \epsilon$, we have

$$\begin{aligned}
 0 < \int_{D(P_0, r)} \Delta u(x, y) \, dx \, dy &= \int_{S(P_0, r)} \partial_n u \, d\sigma \\
 &= \int_0^{2\pi} \frac{\partial}{\partial r} u(x_0 + r \cos \theta, y_0 + r \sin \theta) \, r \, d\theta \\
 &= r \frac{\partial}{\partial r} \int_0^{2\pi} u(x_0 + r \cos \theta, y_0 + r \sin \theta) \, d\theta \\
 &= r \frac{\partial}{\partial r} (2\pi u(x_0, y_0)) = 0.
 \end{aligned}$$

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So, for r less than ϵ , we have this that integral over the disk of Laplacian u is positive because Laplacian u at P_0 was positive and hence we found a disk of radius ϵ on Laplacian u states positive and this by Green's identity is equal to this quantity and this is precisely this and r comes out because integral is with respect to θ and du by du r also comes out what you have inside is precisely something related to mean value. And therefore, what you get is this quantity; this integral is $2\pi u(x_0, y_0)$ which is 0 because this does not depend on r . So, derivative with respect to r is 0.

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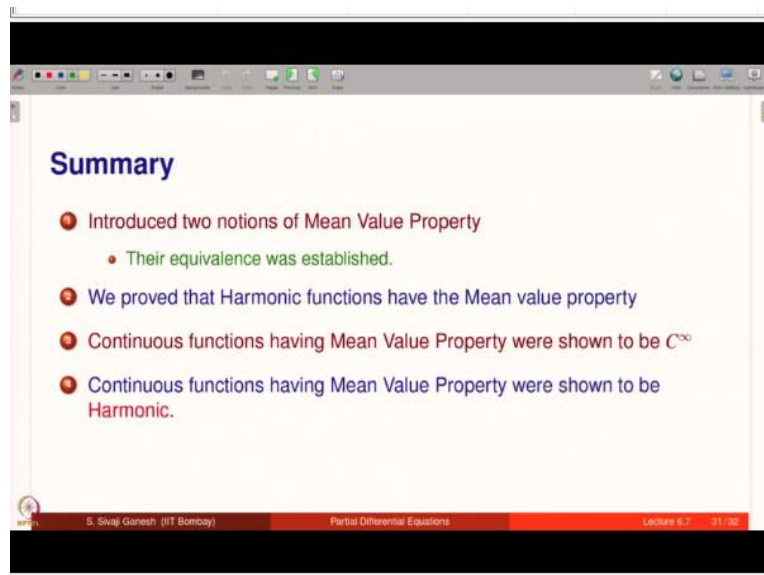
Proof of Theorem (contd.)

- On the last slide, we proved $0 < 0$. This is a contradiction.
- Our assumption that Δu at some point is non-zero is wrong.
- Thus u is a harmonic function on Ω . □

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So, on the last slide what we have got is $0 < 0$, it is a contradiction. Our assumption the Laplacian u at some point is non-zero is wrong. Therefore, u is a harmonic function.

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So, summarize today's lecture, we have introduced 2 notions of mean value property and their equivalence was established. We proved that harmonic functions have the mean value property. We proved that continuous functions having mean value property $r C$ infinity and continuous functions having mean value property are in fact harmonic functions. Thank you.