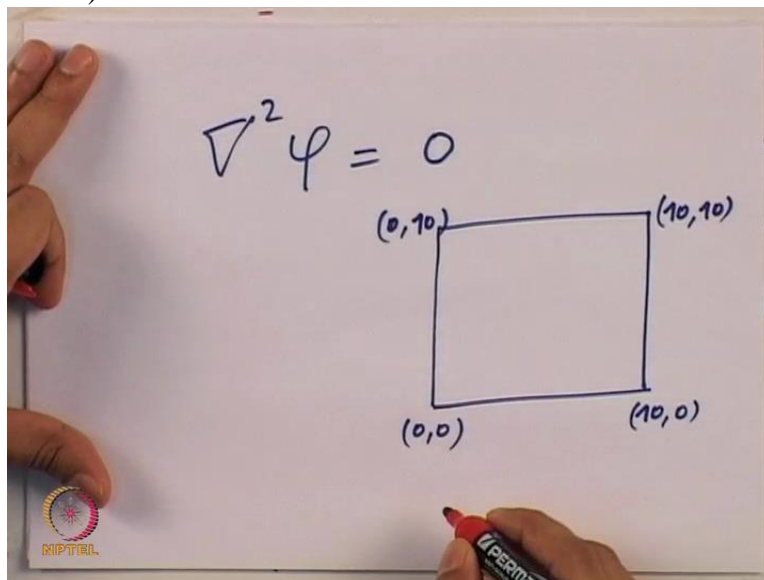


Computational Electromagnetics and Applications
Professor Krish Sankaran
Indian Institute of Technology Bombay
Lecture 04/Exercise 01
Finite Difference Methods –1

So we will look into some exercises in the coming modules. What we will start with is a very simple exercise, dealing with Laplace Equation. So Laplace equation is something that you will come across in every part of the electromagnetic lectures as fundamental equation that deals with potential and how the potential is distributed at given certain boundary conditions. So to understand any differencing method, it is good to start with Laplace Equation as a starting point, and then extend it to Poisson equation which is having certain right hand side term.

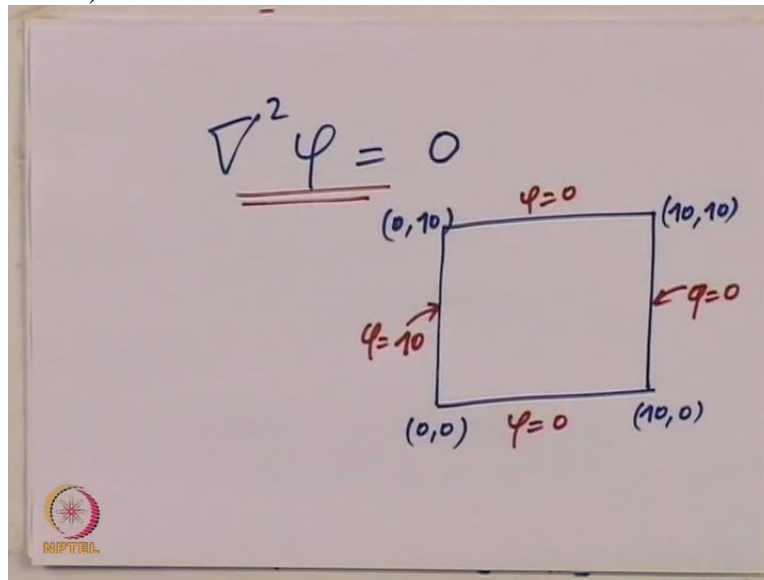
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So we will explain this while we solve the problem. So let us look into the basic equation of Laplace. So what we have is we have the del square phi is equal to 0, and we have certain boundary conditions given. So let us define our domain, our domain is going to be a square with points $(0, 0)$, $(10, 0)$, $(10, 10)$ and $(0, 10)$.

Again I am just defining it for simplicity you can define different domain, dimensions. It need not be a square it can also be a circle so for the simple case let us start with the square domain

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And we are going to define certain boundary conditions the boundary conditions as we discussed before are going to be the definition of potential along these 4 sides. So if we say the potential along these 4 sides are given by certain value.

Let us say we are going to give potential on this particular boundary to be 10. And the potential on this side is going to be zero, so $\phi = 0$ and the potential this side is also zero. So let us take very simple example we see that the potential is going from 10 to 0 and it has to have certain behaviour. Physically we understand that it is going to be a linear drop from 10 to 0. And let us see how numerically it behaves.

(Refer Slide Time: 03:07)

The slide shows the Laplace equation $\nabla^2 \varphi = 0$ with the Laplacian operator ∇^2 circled. Below it, the partial differential equation is written as $\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$. To the right, a square domain is drawn with vertices at $(0,0)$, $(10,0)$, $(10,10)$, and $(0,10)$. The boundary conditions are $\varphi = 0$ on all four sides. An arrow labeled $\varphi = 10$ points to the left side of the square.

So for that we have to start with this particular equation and we have to find difference analogue of this continuous del square. So what we have learnt in the earlier module is we can basically use Central differencing method. So this particular case we can write them as (do square phi by do x square) Plus (do square phi by do y square) is going to be equal to zero. So we have the basic equation in the continuous form written as (do square phi by do x square) plus (do square phi by do y square) equal to zero.

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The slide shows the central difference approximations for the second derivatives. The first equation is $\frac{\partial^2 \varphi}{\partial x^2} \approx \frac{\varphi(i+1, j) - 2\varphi(i, j) + \varphi(i-1, j)}{\Delta x^2}$. The second equation is $\frac{\partial^2 \varphi}{\partial y^2} \approx \frac{\varphi(i, j+1) - 2\varphi(i, j) + \varphi(i, j-1)}{\Delta y^2}$.

What we know from the earlier lectures on finite differencing method, we can approximate the term $\frac{\partial^2 \phi}{\partial x^2}$ by using the Central differencing method as $\frac{\phi(i+1, j) - 2\phi(i, j) + \phi(i-1, j))}{\Delta x^2}$. So what we are doing here is we are doing the central differencing and we are getting the value in this form. Again this is only approximately equal to you have certain truncation errors.

And what we can do similarly is also the other part of the equation which is this one. So we can write it approximately equal to $\frac{\phi(i, j+1) - 2\phi(i, j) + \phi(i, j-1))}{\Delta y^2}$. So this is $\frac{\partial^2 \phi}{\partial x^2}$ and we have $\frac{\partial^2 \phi}{\partial y^2}$ and putting this together what he will get it is the 5 point differencing method where we are using the stencil to compute the value at i, j based on neighbouring points.

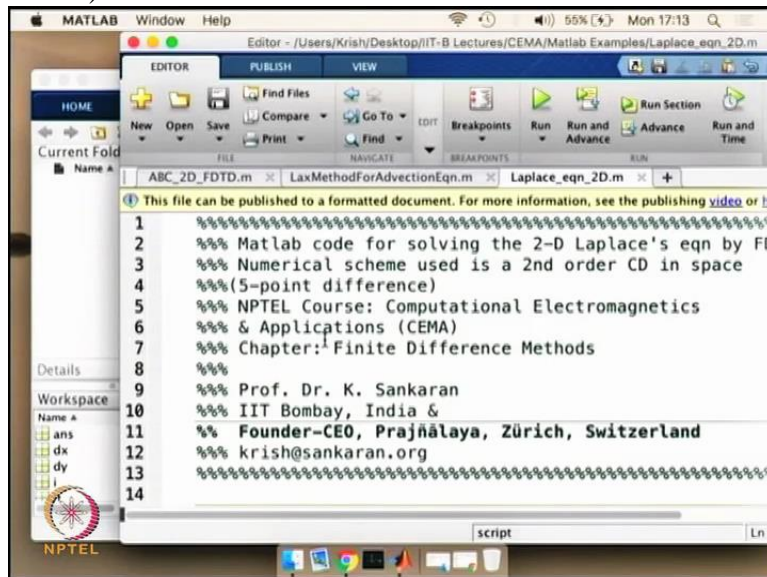
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The image shows a whiteboard with handwritten mathematical expressions and a diagram. The first expression is $\frac{\partial^2 \phi}{\partial x^2} \approx \frac{\phi(i+1, j) - 2\phi(i, j) + \phi(i-1, j))}{\Delta x^2}$. The second expression is $\frac{\partial^2 \phi}{\partial y^2} \approx \frac{\phi(i, j+1) - 2\phi(i, j) + \phi(i, j-1))}{\Delta y^2}$. Below these is a 5-point stencil diagram with a central point labeled i, j and four surrounding points labeled $i-1, j$, $i+1, j$, $i, j+1$, and $i, j-1$. A small logo for NIPTRIL is visible in the bottom left corner of the whiteboard.

So we can write down in this form. So if this is (i, j) this is going to be $(i+1, j)$ this is going to be $(i, j-1)$ this is going to be $(i, j+1)$ this is going to be $(i-1, j)$. And we are computing the value and the center based on certain values at the neighbouring points. So this is what we're going to do in this exercise. We are going to use this 5 point Difference in method to take the Laplace Equation from that continuous space to the finite difference space.

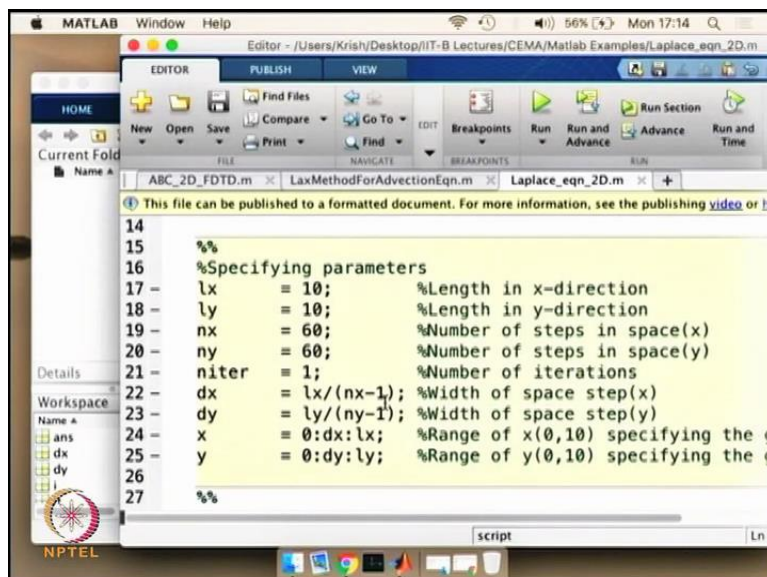
So let us look into the code itself and let us see how the MATLAB program can be used for simply solving this problem. So let us start with the basic MATLAB program.

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The image shows a MATLAB editor window with the following code:

```
1 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
2 %%% Matlab code for solving the 2-D Laplace's eqn by FD
3 %%% Numerical scheme used is a 2nd order CD in space
4 %%% (5-point difference)
5 %%% NPTEL Course: Computational Electromagnetics
6 %%% & Applications (CEMA)
7 %%% Chapter: Finite Difference Methods
8 %%%
9 %%% Prof. Dr. K. Sankaran
10 %%% IIT Bombay, India &
11 %%% Founder-CEO, Prajnālaya, Zürich, Switzerland
12 %%% krish@sankaran.org
13 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
14
```



The image shows a MATLAB editor window with the following code:

```
14
15 %%%
16 %Specifying parameters
17 - lx = 10; %Length in x-direction
18 - ly = 10; %Length in y-direction
19 - nx = 60; %Number of steps in space(x)
20 - ny = 60; %Number of steps in space(y)
21 - niter = 1; %Number of iterations
22 - dx = lx/(nx-1); %Width of space step(x)
23 - dy = ly/(ny-1); %Width of space step(y)
24 - x = 0:dx:lx; %Range of x(0,10) specifying the g
25 - y = 0:dy:ly; %Range of y(0,10) specifying the g
26
27 %%%
```

So now let us look into the code itself. So we are setting certain specifications. So these are the specifications which we will use to set the dimensions and the parameters of the problem. So the first one is the l_x which is the length in the X direction and the second one is the l_y which is the length in Y direction, which is very similar to the problem which we have in the paper.

As you can see, so the length in x direction is 10, the length in Y direction is also 10 and that is what we have set here. And n_x and n_y are going to be the number of steps in X and Y direction. So we have 60 steps in x, and 60 steps in y. And the number of iterations are going to be given by N theta and as you can see I have given here wantedly. The reason is one will be a very very crude approximation and we will see how to increase and why we have to increase to get better resolution.

Δx is going to be the width of the step in X and Y direction will be Δy . So Δx and Δy are correspondingly the width of the steps, or stepping size in X and Y direction. And the value of various X component and Y component are given by the X and Y parameters. And they are going to go from 0 to l_x with a steps size of Δx in the direction of x, similarly they are going to go from 0 to l_y with step size of Δy in the direction of y.

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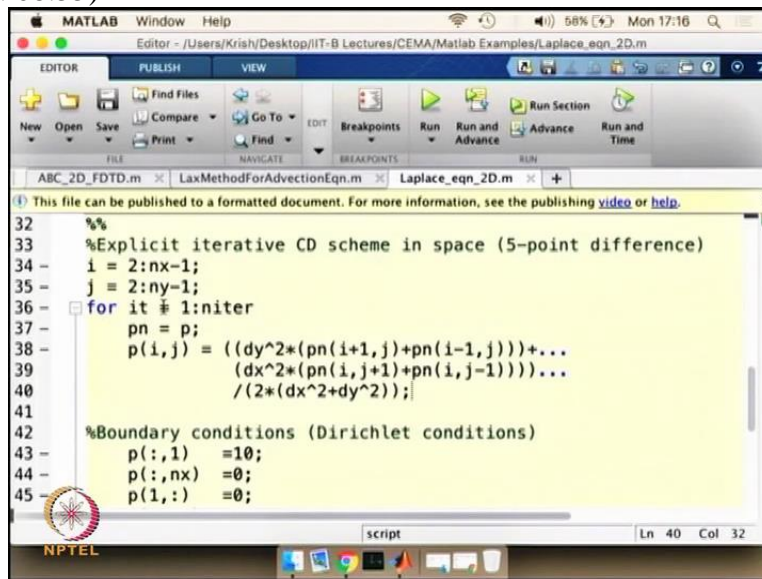
```

25 - y = 0:dy:ly; %Range of y(0,10) specifying the grid pts
26
27 %%
28 %Initial Conditions
29 - p = zeros(ny,nx); %Pre-allocating p
30 - pn = zeros(ny,nx); %Pre-allocating pn
31
32 %%
33 %Explicit iterative CD scheme in space (5-point difference)
34 - j = 2:nx-1;
35 - i = 2:ny-1;
36 - for it = 1:niter
37 -     pn = p;
38 -     p(i,j) = ((dy^2*(pn(i+1,j)+pn(i-1,j)))+...

```

So now we are initializing certain parameters for example potential is given by p here, we are preallocating them to be 0 and p n is also a variable we are going to use and we are preallocating it to 0. And we are going to go into the iteration the one which I explained you in the paper.

(Refer Slide Time: 08:55)



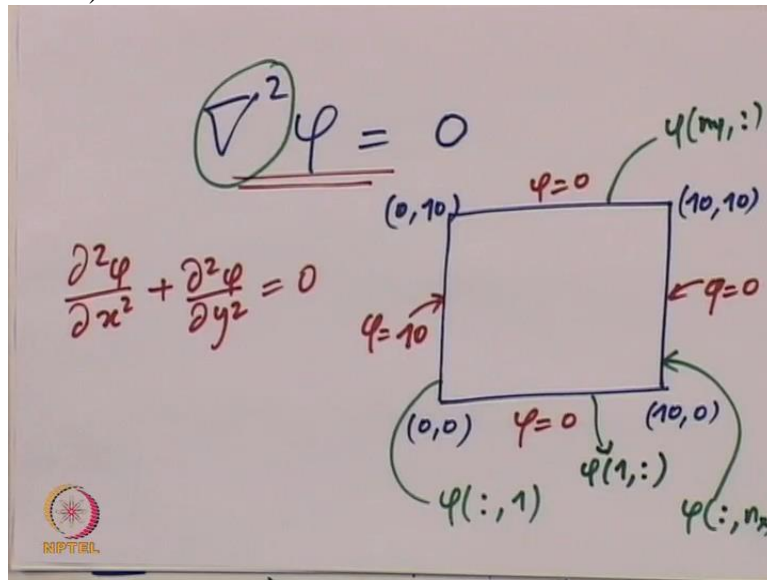
```
32 %%
33 %Explicit iterative CD scheme in space (5-point difference)
34 - i = 2:nx-1;
35 - j = 2:ny-1;
36 - for it = 1:niter
37 -     pn = p;
38 -     p(i,j) = ((dy^2*(pn(i+1,j)+pn(i-1,j)))+...
39 -             (dx^2*(pn(i,j+1)+pn(i,j-1))))...
40 -             /(2*(dx^2+dy^2));
41
42 %Boundary conditions (Dirichlet conditions)
43 - p(:,1) = 10;
44 - p(:,nx) = 0;
45 - p(1,:) = 0;
```

So we see that we are going to use a 5 point Central differencing scheme which I explained to you just now in the paper. We are going to go with certain index which is i for the X co-ordinate and j for the Y coordinate. And the iteration is going to be the for loop and it goes from 1 to number of iterations. In our case initially we have chosen $niter$ equal to 1.

And you and we'll see that it is not going to give us good result but still we will start with that. And now we are using the central differencing scheme. I just explained on the paper to compute $p_{i,j}$ using the points surrounding it and we are going to use the 5 points for that. So basically we are taking the four neighbouring points to compute the value and center point that is why we are calling them 5 point Difference.

And we have set the boundary conditions as given here so we have set $p(\text{dash}, 1)$ equal to 10. So what I say ($\text{dash}, 1$) is it is going to be for all x coordinates but with 1 Y coordinate, the one Y coordinate going to be Y equal to 1 so its going to be a line that is going to be at Y equal to 1.

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So Y equal to 1 will be the first coordinate which we have given here so this is going to be the first Y coordinates, and similarly this is going to be the last Y coordinate which is going to be n_y . So let us write it down. So this is going to be the $\phi(\text{dash}, 1)$ and this is going to be $\phi(\text{dash}, n_x)$, similarly we can write them also for the other two sides. So this is going to be $\phi(n_y, \text{dash})$ and similarly this is going to be the $\phi(1, \text{dash})$.

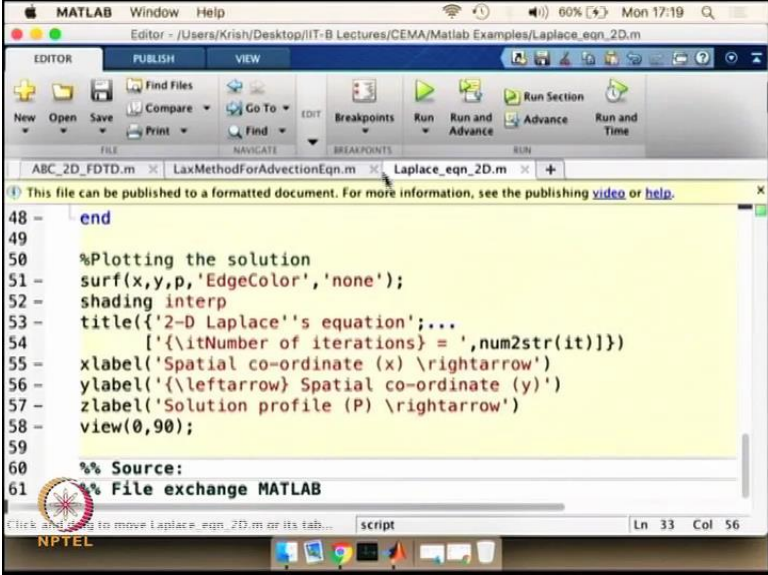
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```
33 %Explicit iterative CD scheme in space (5-point difference)
34 - i = 2:nx-1;
35 - j = 2:ny-1;
36 - for it = 1:niter
37 -     pn = p;
38 -     p(i,j) = ((dy^2*(pn(i+1,j)+pn(i-1,j)))+...
39 -             (dx^2*(pn(i,j+1)+pn(i,j-1))))...
40 -             /(2*(dx^2+dy^2));
41
42 %Boundary conditions (Dirichlet conditions)
43 - p(:,1) = 10;
44 - p(:,nx) = 0;
45 - p(1,:) = 0;
46 - p(ny,:) = 0;
```

So that is what we have done here so if we see the equation we have put for the first y line as equal to 10. So this is going to be the line that is going at Y equal to zero. So Y equal to zero will be the the first coordinate since we are in the loop going from the value we are setting the value

ok i, j but we are not worried about the first coordinates because we are setting the value of boundary conditions. Since the boundary conditions are going to be the first co-ordinate or the last co-ordinate for loop is only going from in between values. So the first value and the last value are actually the boundary coordinates which we are considering here if you may be wondering why we start from 2 to n_x minus 1 or 2 to n_y minus 1 the reason is here, in the boundary coordinates.

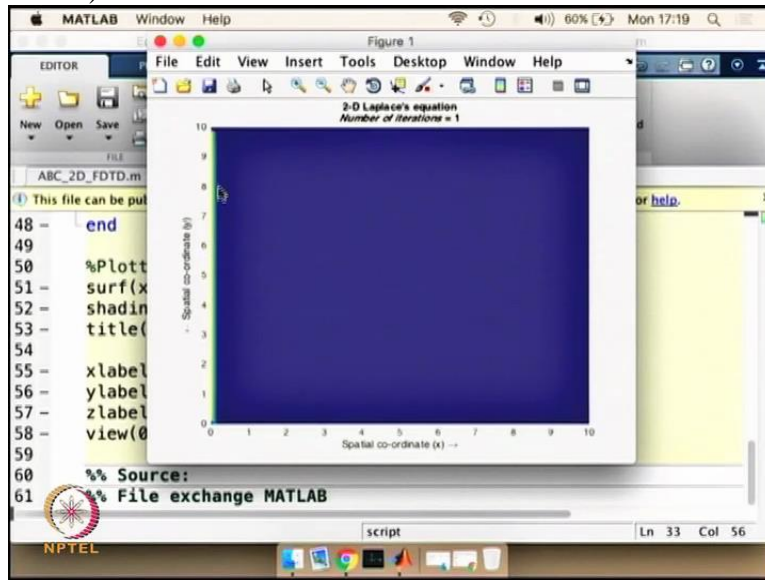
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```
48 - end
49
50 %Plotting the solution
51 - surf(x,y,p,'EdgeColor','none');
52 - shading interp
53 - title({'2-D Laplace's equation';...
54 -       ['\itNumber of iterations = ',num2str(it)]})
55 - xlabel('Spatial co-ordinate (x) \rightarrow')
56 - ylabel('\leftarrow Spatial co-ordinate (y)')
57 - zlabel('Solution profile (P) \rightarrow')
58 - view(0,90);
59
60 %% Source:
61 %% File exchange MATLAB
```

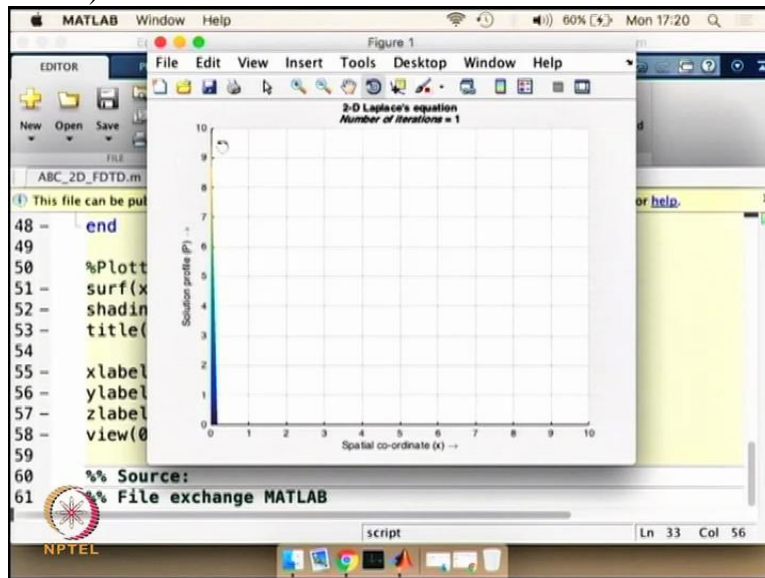
So let us run this program what we are going to plot is the value of the potential ϕ as a function of x, y and we are going to see it in the top view and we can rotate it and see also in the other views.

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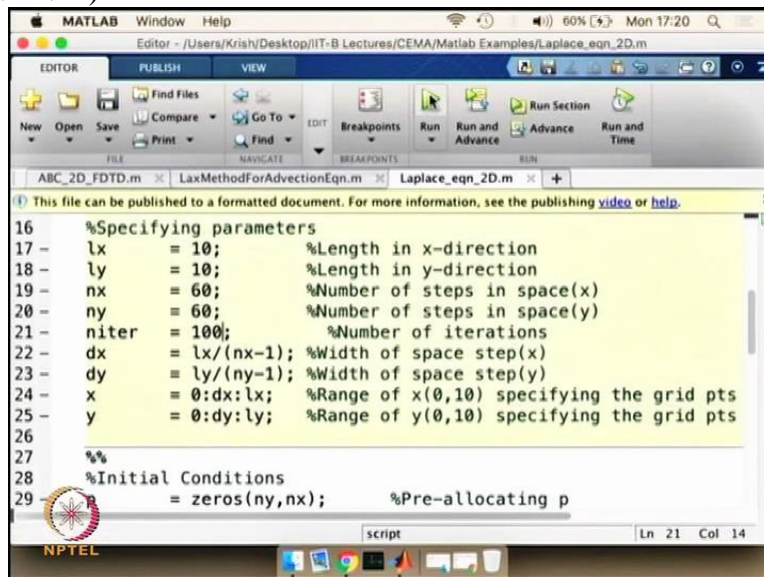
So once you run it you see that the potential on the left hand side I can rotate it so this is the top view we are on the xy plane so if we view it from xz plane you will see it is showing that the potential is 10 on the left hand side but the other potential immediately drops to 0 which is not physical.

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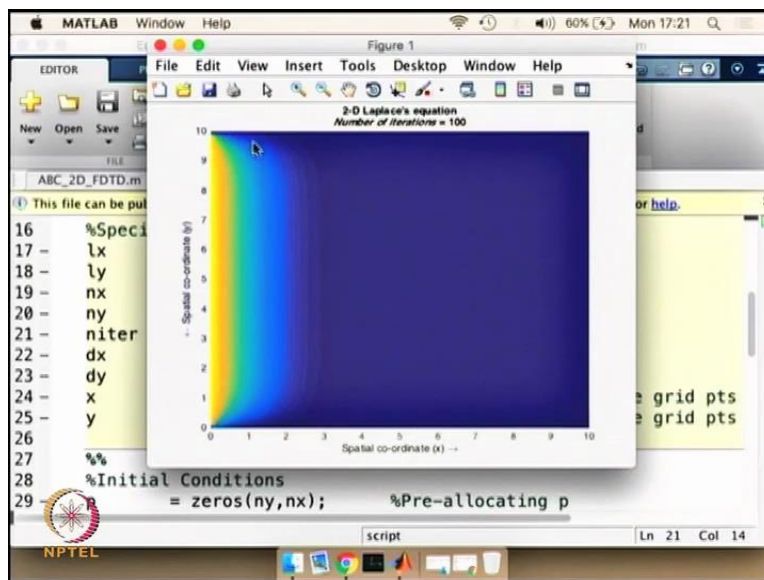


What we expect theoretically is a kind of a equipotential lines and we will see where the equipotential lines are by simulating the problem for more iteration. So let us go and iterate it for let us say 100 iterations.

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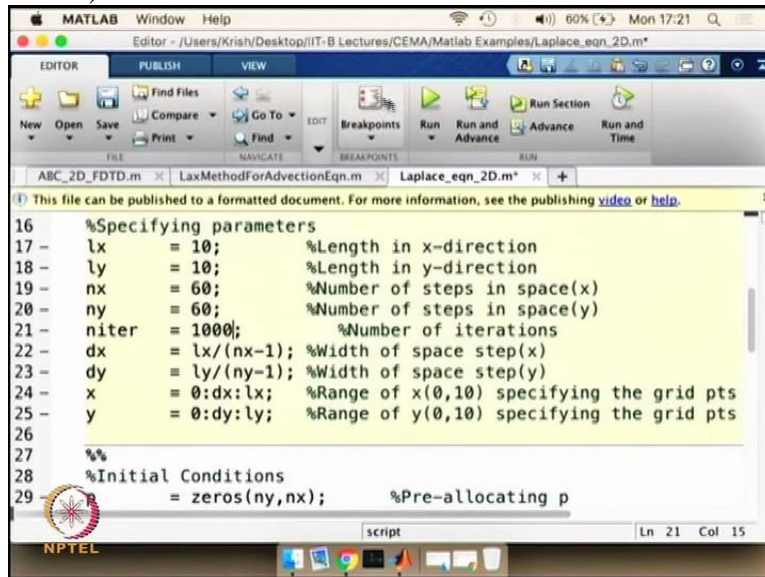


```
16 %Specifying parameters
17 - lx = 10; %Length in x-direction
18 - ly = 10; %Length in y-direction
19 - nx = 60; %Number of steps in space(x)
20 - ny = 60; %Number of steps in space(y)
21 - niter = 100; %Number of iterations
22 - dx = lx/(nx-1); %Width of space step(x)
23 - dy = ly/(ny-1); %Width of space step(y)
24 - x = 0:dx:lx; %Range of x(0,10) specifying the grid pts
25 - y = 0:dy:ly; %Range of y(0,10) specifying the grid pts
26
27 %%
28 %Initial Conditions
29 = zeros(ny,nx); %Pre-allocating p
```

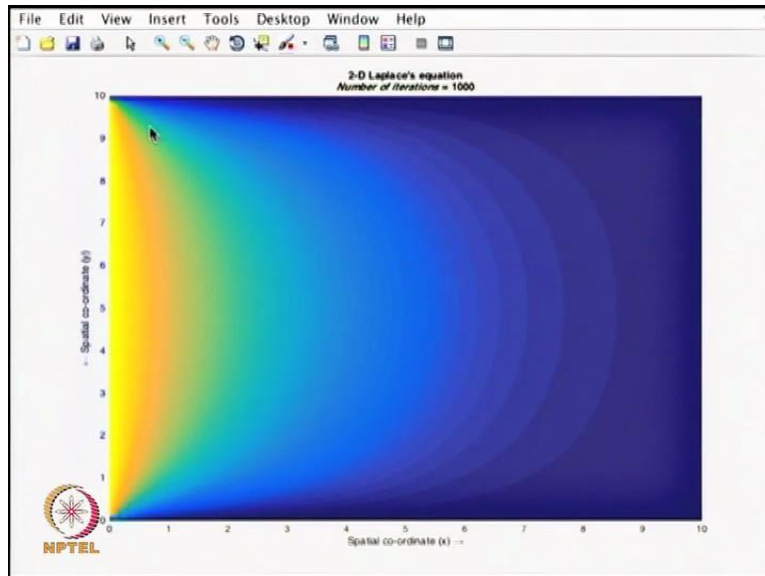


So I am putting iteration is equal to 100 and running it and you see that since this boundary and this boundary is also zero we will see a kind of a equipotential line and let us see running it for longer time let us say I am running it for 1000 iterations.

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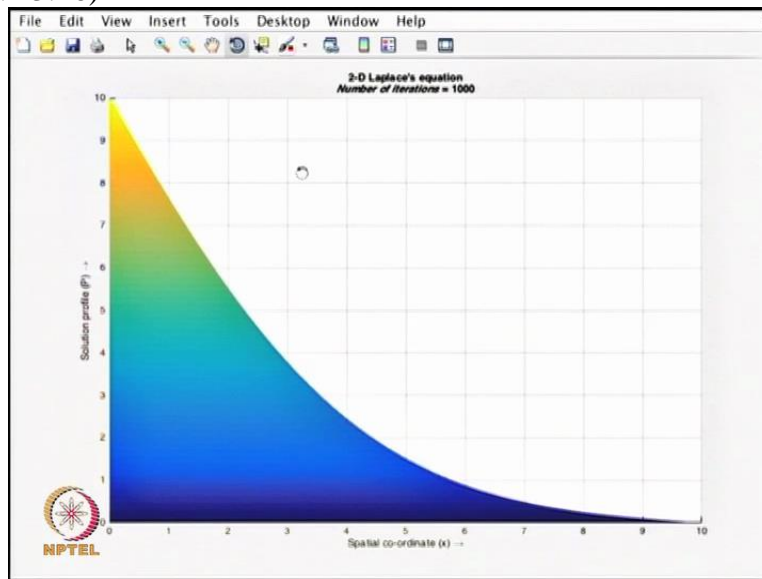


```
16 %Specifying parameters
17 lx = 10; %Length in x-direction
18 ly = 10; %Length in y-direction
19 nx = 60; %Number of steps in space(x)
20 ny = 60; %Number of steps in space(y)
21 niter = 1000; %Number of iterations
22 dx = lx/(nx-1); %Width of space step(x)
23 dy = ly/(ny-1); %Width of space step(y)
24 x = 0:dx:lx; %Range of x(0,10) specifying the grid pts
25 y = 0:dy:ly; %Range of y(0,10) specifying the grid pts
26
27 %%
28 %Initial Conditions
29 p = zeros(ny,nx); %Pre-allocating p
```



I am seeing that it is replicating but still I can see the equipotential lines. I will zoom it out, you will see the equipotential lines seen as those different shades of colors and if we rotate it in a different plane you will start to see a drop that is happening.

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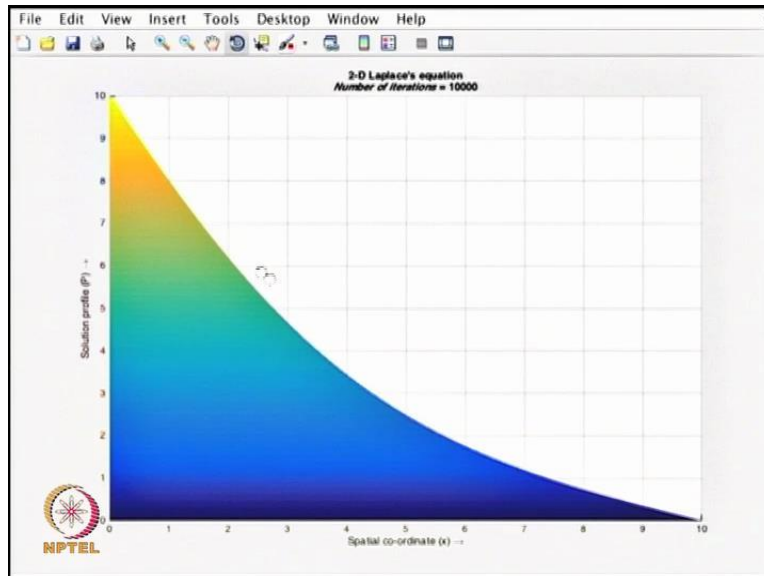
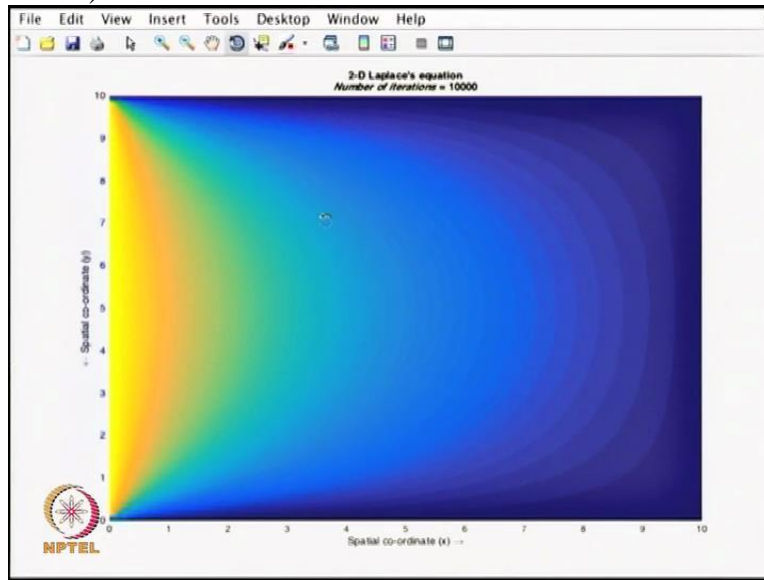
```
MATLAB Window Help
Editor - /Users/Krist/Desktop/IIT-B Lectures/CEMA/Matlab Examples/Laplace_eqn_2D.m*

EDITOR PUBLISH VIEW
New Open Save Find Files Compare Go To EDIT Breakpoints Run Run and Advance Run and Time
Print Find NAVIGATE BREAKPOINTS RUN
ABC_2D_FDTD.m x LaxMethodForAdvectionEqn.m x Laplace_eqn_2D.m* x +
This file can be published to a formatted document. For more information, see the publishing video or help.
16 %Specifying parameters
17 - lx = 10; %Length in x-direction
18 - ly = 10; %Length in y-direction
19 - nx = 60; %Number of steps in space(x)
20 - ny = 60; %Number of steps in space(y)
21 - niter = 10000; %Number of iterations
22 - dx = lx/(nx-1); %Width of space step(x)
23 - dy = ly/(ny-1); %Width of space step(y)
24 - x = 0:dx:lx; %Range of x(0,10) specifying the grid pts
25 - y = 0:dy:ly; %Range of y(0,10) specifying the grid pts
26
27 %%
28 %Initial Conditions
29 = zeros(ny,nx); %Pre-allocating p

script Ln 21 Col 16
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```

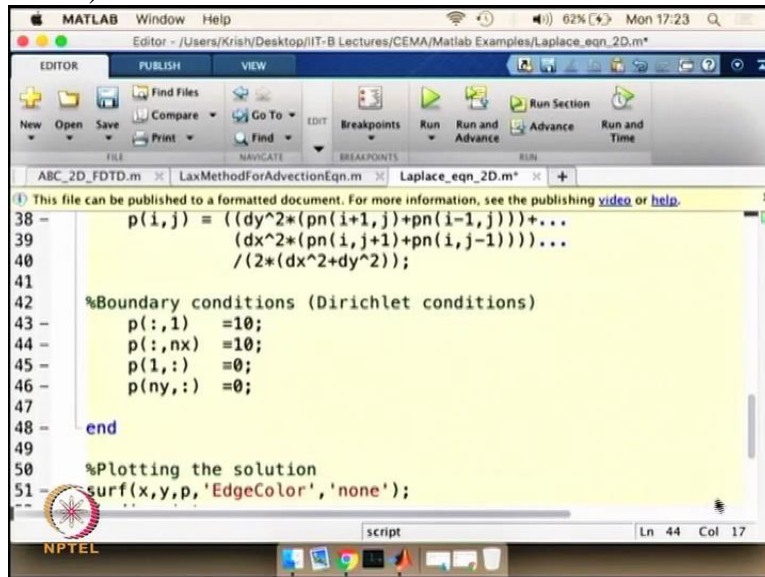
So now if you run the same thing for more number of iterations let us say we run it for 10000 iterations which should be good enough.

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Now we can see the quality of result is improving and we are able to see a drop which is as we expect. So this is Laplace equation for this particular case what we can try doing is we can try changing the boundary conditions In order to see what will be the influence of the boundary conditions for this particular problem. So what I am going to do is instead of choosing 0 on other side I am going to choose certain values. For example let us say my two edges.

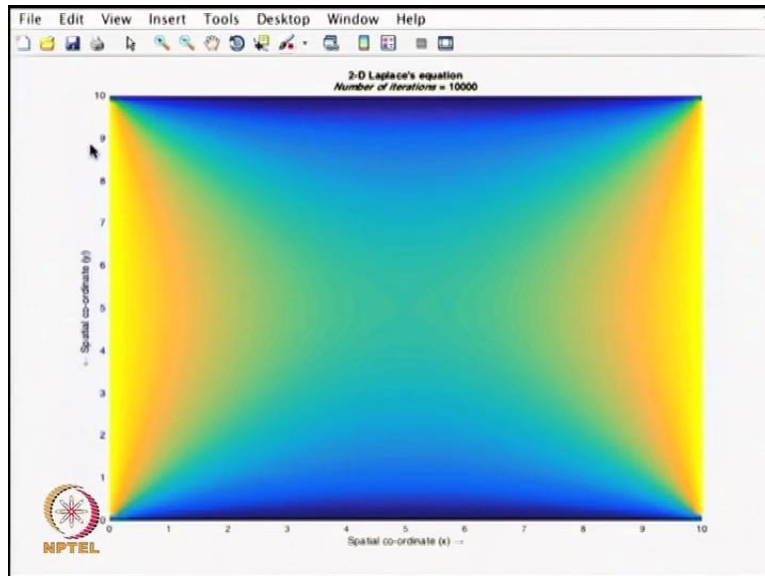
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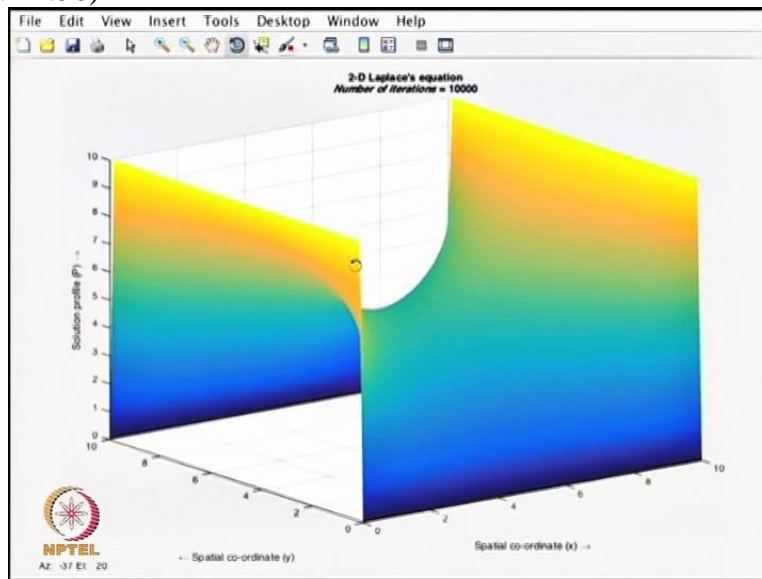
EDITOR PUBLISH VIEW
New Open Save Find Files Compare Go To Breakpoints Run Run and Advance Run Section Run and Time
FILE NAVIGATE BREAKPOINTS RUN

ABC_2D_FDTD.m LaxMethodForAdvectionEqn.m Laplace_eqn_2D.m*
1 This file can be published to a formatted document. For more information, see the publishing video or help.
38 - p(i,j) = ((dy^2*(pn(i+1,j)+pn(i-1,j)))+...
39 - (dx^2*(pn(i,j+1)+pn(i,j-1))))...
40 - / (2*(dx^2+dy^2));
41
42 %Boundary conditions (Dirichlet conditions)
43 - p(:,1) =10;
44 - p(:,nx) =10;
45 - p(1,:) =0;
46 - p(ny,:) =0;
47
48 - end
49
50 %Plotting the solution
51 - surf(x,y,p,'EdgeColor','none');
--
```



So for y equal to 0 and y equal to 10 which is these two edges I am going to put the value as 10 and the other two I keep it as 0. And I am going to run it for 10000 iterations steps and when I do that I start to see a nice curve of the equipotential lines. What we see is potential lines are following certain pattern and you will see that pattern here.

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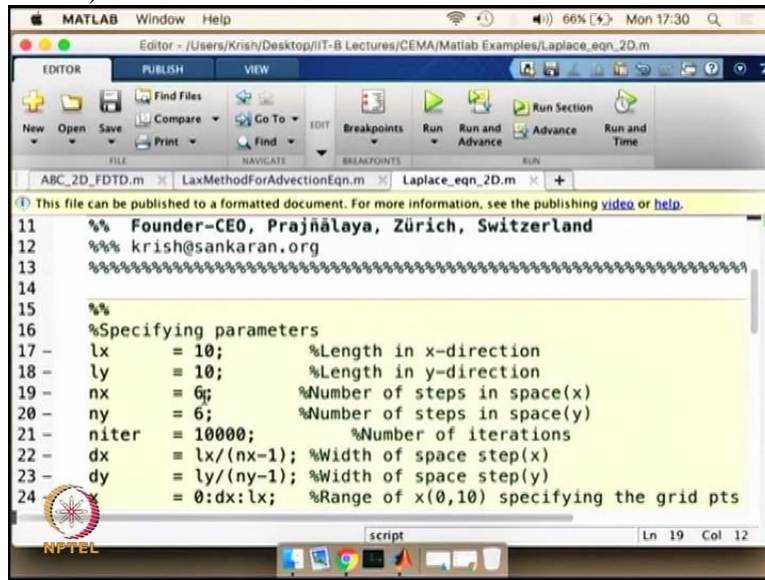


So the value here is set to 10 the value here is set to 10 whereas value on these two boundaries are set to 0 and you see a nice manifold of the potential and you see the equipotential surface when you see it from the top view. So these are the equipotential surface.

And So this is a very good example for you to start with because this gives us certain understanding of how a single equation as Laplace equation can be simulated using matlab and using certain central differencing scheme which we learnt in the previous modules and this is going to be a very important exercise for you because we are going to build on this exercise in the next step using Poisson equation.

And Poisson equation will be same as the Laplace equation except the fact that we have a right hand side term which will not be equal to 0 so we will have certain influence from the right hand side term which we will see in the next module. We can see that already in this particular case where we can define the value of dx and dy accordingly.

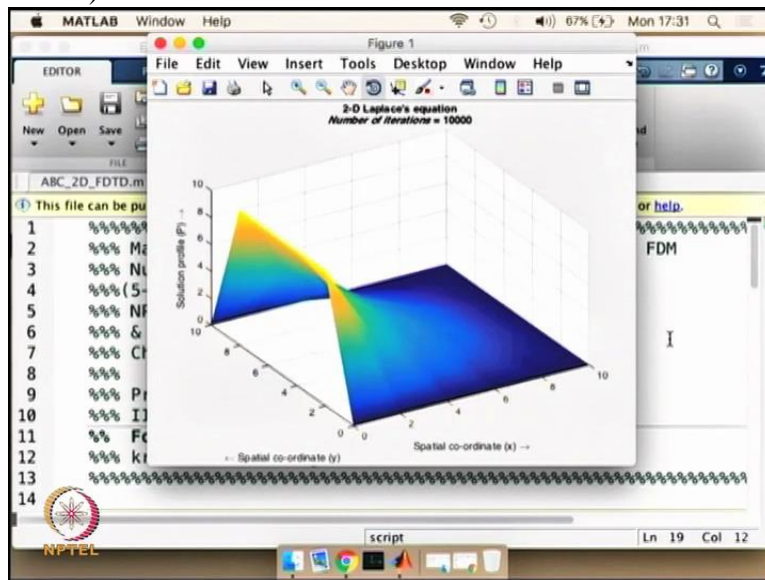
(Refer Slide Time: 16:26)



```
11 %% Founder-CEO, Prajnālaya, Zürich, Switzerland
12 %% krish@sankaran.org
13 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
14
15 %%
16 %Specifying parameters
17 - lx = 10; %Length in x-direction
18 - ly = 10; %Length in y-direction
19 - nx = 6; %Number of steps in space(x)
20 - ny = 6; %Number of steps in space(y)
21 - niter = 10000; %Number of iterations
22 - dx = lx/(nx-1); %Width of space step(x)
23 - dy = ly/(ny-1); %Width of space step(y)
24 - x = 0:dx:lx; %Range of x(0,10) specifying the grid pts
```

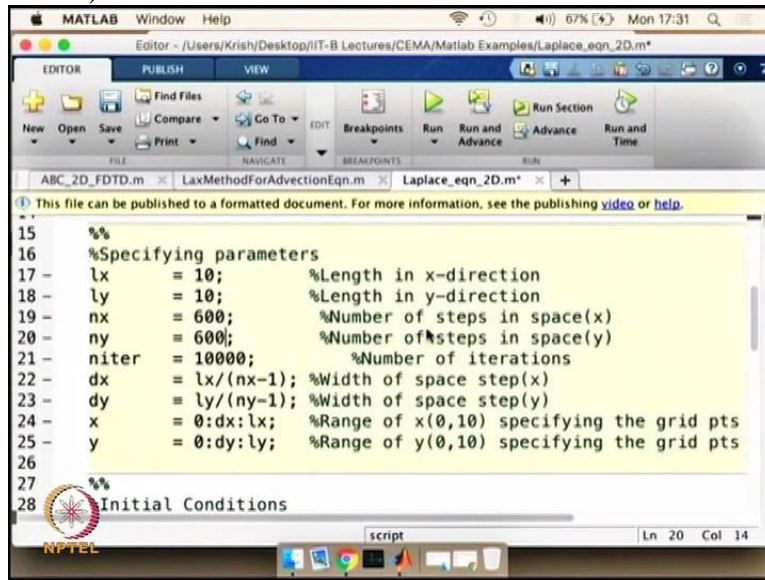
So if we choose we want the number of special discretization to be in particular manner for example if we choose instead of 60 6 points on the x and y direction we will see the influence of the problem resolution will change accordingly. Let us run this code initially we had 60 and we changed it into 6 and if we run the same program and we are giving the boundary conditions to be 10,0 and 0 on other sides and if we run it you will see the result is going to be categorically different in terms of quality.

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You will see that the equipotential lines are not really symmetrical. There is going to be some influence in certain directions.

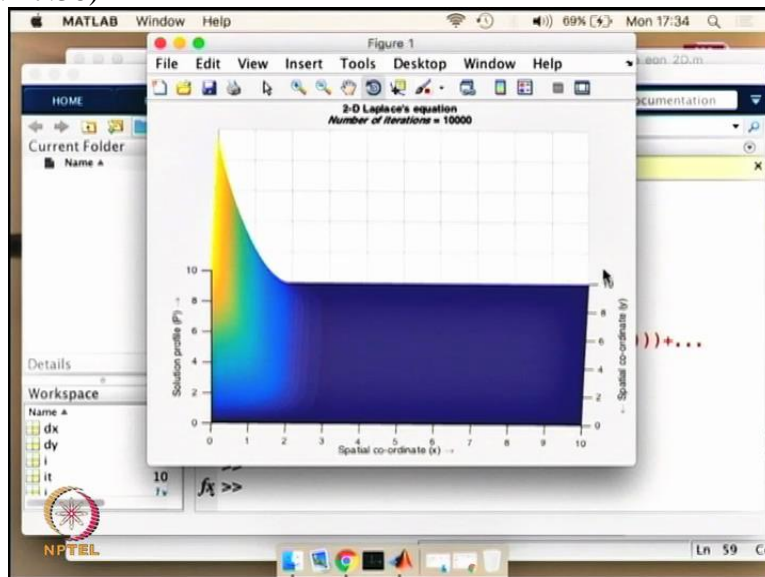
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```
15 %%
16 %Specifying parameters
17 - lx = 10; %Length in x-direction
18 - ly = 10; %Length in y-direction
19 - nx = 600; %Number of steps in space(x)
20 - ny = 600; %Number of steps in space(y)
21 - niter = 10000; %Number of iterations
22 - dx = lx/(nx-1); %Width of space step(x)
23 - dy = ly/(ny-1); %Width of space step(y)
24 - x = 0:dx:lx; %Range of x(0,10) specifying the grid pts
25 - y = 0:dy:ly; %Range of y(0,10) specifying the grid pts
26
27 %%
28 Initial Conditions
```

And if we keep this one aside and I am going to run the same program with higher number of discretization. Let us say I am going to increase it with 600 I am going to run the same code so what we see here is compared to the earlier problem where we had only 60 steps in the x and y direction now we have increased the number of steps to 10 times more and we can see the result is much more finer.

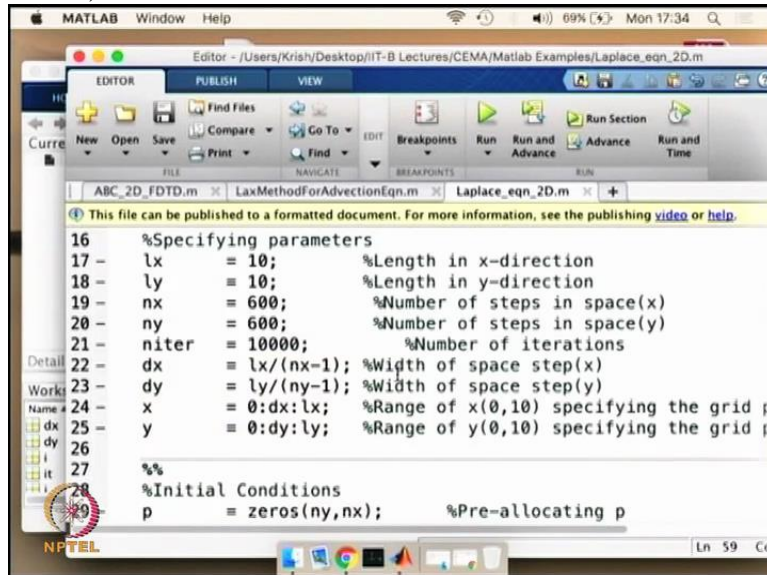
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So the resolution of the result is better compared to the previous simulation. So what we are trying to illustrate here is there is going to be an impact of the spatial and temporal discretization and also the number of iteration that you are going to run on the top of the

differencing method scheme itself. So there is going to be an impact of differencing method and on the top of the impact of the differencing method the simulation parameters what we are going to use will influence the resolution or the quality of your solution.

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```
16 %Specifying parameters
17 - lx = 10; %Length in x-direction
18 - ly = 10; %Length in y-direction
19 - nx = 600; %Number of steps in space(x)
20 - ny = 600; %Number of steps in space(y)
21 - niter = 10000; %Number of iterations
22 - dx = lx/(nx-1); %Width of space step(x)
23 - dy = ly/(ny-1); %Width of space step(y)
24 - x = 0:dx:lx; %Range of x(0,10) specifying the grid p
25 - y = 0:dy:ly; %Range of y(0,10) specifying the grid p
26
27 %%
28 %Initial Conditions
29 p = zeros(ny,nx); %Pre-allocating p
```

So that is a classical example for you to try, so we want you to use this particular code and try it for yourself how the central differencing scheme is implemented in Matlab for Poisson or in Laplace equation. In this case we have used for Laplace equation. We will try doing the same problem also in the case of Poisson equation to see how the right hand side can be implemented in Matlab and I would like you to see how you can manipulate the special discretization in the x and y direction and also the number of iteration that we are going to use. So that we you get a holistic understanding not only about the discretization method not only about the differencing method but also about the simulation parameter and it's influence on the numerical result. So with that being said I think we will stop here and we will come back in the next example and look at Poissonequation. Thank you!